

ERRATUM

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<https://doi.org/10.1002/rob.21917>

In Kaljaca, Vroegindeweij, and van Henten (2020), there is a change in the author group, name of one of the author, Angelo Mencarelli, was accidentally removed from the author list and needs to be added back. This article was published in *Journal of Field Robotics* in February 2020 (<https://doi.org/10.1002/rob.21917>).

We apologize for the error.

Updated author group is:

Dejan Kaljaca, Bastiaan Vroegindeweij, Angelo Mencarelli, and Eldert van Henten

with the following affiliation for Angelo Mencarelli:

Stichting Wageningen Research, Wageningen University & Research, Wageningen, The Netherlands.

REFERENCE

Kaljaca, D., Vroegindeweij, B., & van Henten, E. (2020). Coverage trajectory planning for a bush trimming robot arm. *J Field Robotics*, 37, 283–308. <https://doi.org/10.1002/rob.21917>