



Improved monitoring of shipping NO₂ with TROPOMI: decreasing NO_x emissions in European seas during the COVID-19 pandemic

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Abstract. TROPOMI (TROPOspheric Monitoring Instrument) measurements of tropospheric NO₂ columns provide powerful information on emissions of air pollution by ships on open sea. This information is potentially useful for authorities to help determine the (non-)compliance of ships with increasingly stringent NO_x emission regulations. We find that the information quality is improved further by recent upgrades in the TROPOMI cloud retrieval and an optimal data selection. We show that the superior spatial resolution of TROPOMI allows for the detection of several lanes of NO₂ pollution ranging from the Aegean Sea near Greece to the Skagerrak in Scandinavia, which have not been detected with other satellite instruments before. Additionally, we demonstrate that under conditions of sun glint TROPOMI's vertical sensitivity to NO₂ in the marine boundary layer increases by up to 60%. The benefits of sun glint are most prominent under clear-sky situations when sea surface winds are low but slightly above zero ($\pm 2 \text{ m s}^{-1}$). Beyond spatial resolution and sun glint, we examine for the first time the impact of the recently improved cloud algorithm on the TROPOMI NO₂ retrieval quality, both over sea and over land. We find that the new FRESCO+ (Fast Retrieval Scheme for Clouds from the Oxygen A band) wide algorithm leads to 50 hPa lower cloud pressures, correcting a known high bias, and produces $1\text{--}4 \times 10^{15} \text{ molec. cm}^{-2}$ higher retrieved NO₂ columns, thereby at least partially correcting for the previously reported low bias in the TROPOMI NO₂ product. By training an artificial neural network on the four available periods with standard and FRESCO+ wide test retrievals, we develop a

historic, consistent TROPOMI NO₂ data set spanning the years 2019 and 2020. This improved data set shows stronger (35%–75%) and sharper (10%–35%) shipping NO₂ signals compared to co-sampled measurements from OMI. We apply our improved data set to investigate the impact of the COVID-19 pandemic on ship NO₂ pollution over European seas and find indications that NO_x emissions from ships reduced by 10%–20% during the beginning of the COVID-19 pandemic in 2020. The reductions in ship NO₂ pollution start in March–April 2020, in line with changes in shipping activity inferred from automatic identification system (AIS) data on ship location, speed, and engine.

1 Introduction

Emissions of nitrogen oxides (NO_x = NO + NO₂) have several primary and secondary effects on air quality, human health, and the environment. NO_x is a toxic gas itself (WHO, 2003) and contributes to the formation of secondary pollutants and ozone. Ozone close to the Earth's surface is a toxic pollutant which can lead to respiratory problems and has negative effects on plant growth and crop yield (e.g., Wang and Mauzerall, 2004). NO_x also contributes to acid deposition and eutrophication, harming sensitive ecosystems (European Environment Agency, 2019).

The international shipping sector is a strong source of NO_x and other air pollutants to the atmosphere (e.g., Eyring et al., 2010). Previous studies suggest that international ship-

ping makes up annual emissions of 2.0–10.4 TgN (Crippa et al., 2018; Eyring et al., 2010; Johansson et al., 2017) or 15 %–35 % of total anthropogenic NO_x emissions worldwide. While cars, the power sector, and industry have shown substantial reductions in their emissions over the last 10–20 years in Europe and the United States (Curier et al., 2014; Hassler et al., 2016), NO_x emissions from shipping activity have increased (De Ruyter de Wildt et al., 2012; Boersma et al., 2015), and the number of ship movements and ship size are expected to keep increasing in the future (Eyring et al., 2005; UNCTAD, 2019). Shipping-related air pollution emissions are estimated to lead to 60 000 premature deaths annually, especially in coastal regions (Corbett et al., 2007; Marais et al., 2015).

To mitigate these and other harmful impacts, more stringent regulations on NO_x emissions for ships have been implemented in coastal regions and on the open ocean (IMO, 2013). For example, ships built in 2011 or later have to follow Tier II nitrogen emission regulation as defined in MARPOL Annex VI. In so-called Emission Control Areas (ECAs) even more stringent rules apply. From 1 January 2021 onwards, the new MARPOL Annex VI regulation 13 determines that newly built ship engines should be compliant with Tier III in the new ECA in the Baltic and North Sea, which should result in 75 % lower NO_x emissions from new ships. The exact limits depend on ship engine speed (IMO, 2013); see Sect. S1 in the Supplement.

For new regulations to be effective, monitoring and verification of ship emissions are required. Traditional compliance monitoring includes national authorities conducting on-board checks of engine certificates and keel-laying date. This is not a direct verification of emissions and can only be done for a limited number of vessels. Other methods are onboard measurements at the ship's exhaust pipe (e.g., Agrawal et al., 2008) or downwind measurements of emission plumes using sniffer techniques or DOAS (differential optical absorption spectroscopy) measurements (e.g., Lack et al., 2009; Berg et al., 2012; McLaren et al., 2012; Pirjola et al., 2014; Seyler et al., 2019). Modern techniques also include airborne platforms such as helicopters, small aircraft (Mellqvist and Conde, 2021; Chen et al., 2005a), or drones (Van Roy and Scheldeman, 2016). While these methods do not require inspectors to board the vessel, they require proximity to the ships monitored and are thus less fit-for-purpose when a large number of ships is to be checked or on open sea away from land. For the above reasons monitoring by satellite remote sensing offers a promising alternative.

Satellite instruments have observed enhancements of NO₂ column densities over major shipping routes, e.g., from GOME (Beirle et al., 2004), SCIAMACHY (Richter et al., 2004), and OMI (Vinken et al., 2014b; Marmer et al., 2009). These satellite measurements have recently been continued with new observations from the TROPOMI (TROPospheric Monitoring Instrument) sensor. With a pixel size of 3.5 km × 5.5 km TROPOMI provides a spatially more re-

solved evaluation of NO₂ pollution patterns compared to its predecessors GOME (40 km × 320 km), SCIAMACHY (30 km × 60 km), and OMI (13 km × 24 km). Indeed, previous studies demonstrated TROPOMI's capability to pinpoint emissions from the mining industry (Griffin et al., 2019), emissions patterns within cities (Beirle et al., 2019; Lorente et al., 2019), emissions along a gas pipeline in Siberia (van der A et al., 2020), and even from individual ships in the Mediterranean Sea (Georgoulias et al., 2020). Ding et al. (2020) used TROPOMI NO₂ columns and inverse modeling to show NO_x emission reductions during the COVID-19 lockdown over urban centers and regions with strong maritime transport.

While the aforementioned studies demonstrate the large potential of TROPOMI and its high resolution, retrieval problems remain. Validation studies (e.g., Griffin et al., 2019; Verhoelst et al., 2021) suggest a 15 %–40 % low bias in TROPOMI tropospheric vertical NO₂ ($N_{v,trop}$) columns relative to independent in situ and MAX-DOAS (multi-axis differential optical absorption spectroscopy) measurements. Cloud properties present one of the leading sources of uncertainty in trace gas retrieval from space (Boersma et al., 2004; Lorente et al., 2017), and cloud heights used until (and including) v1.3 of the operational TROPOMI retrieval algorithm have been suggested to be biased low (Compernelle et al., 2021). To address this bias in cloud heights, the Royal Dutch Meteorological Institute (KNMI) recently updated the FRESCO+ (Fast Retrieval Scheme for Clouds from the Oxygen A band) cloud retrieval by widening the spectral window, which is supposed to improve the sensitivity to low clouds.

The here-presented study presents and assesses the impact of steps towards an improved monitoring of shipping NO₂ with TROPOMI. First, we demonstrate TROPOMI's capability to detect ship emissions applying a typical data selection and compare it to OMI's. We examine previous suggestions of improved retrieval sensitivity over sun glint scenes (Georgoulias et al., 2020). Additionally, we evaluate the new FRESCO+ wide cloud pressure retrieval and its impact on the TROPOMI NO₂ columns in v1.4–2.1 of the operational TROPOMI NO₂ algorithm. Based on our findings, we create a data set of historical TROPOMI NO₂ columns consistent with the v1.4 data allowing for otherwise challenging trend analysis. We conclude with an application of our findings to quantify the effects of the COVID-19 pandemic on ship pollution, a unique opportunity to assess the relationship between the anticipated emission reductions and observed NO₂ columns.

2 Methods and materials

2.1 TROPOMI and OMI NO₂ column measurements

The European TROPOMI (Veefkind et al., 2012) is on board the Sentinel-5 Precursor launched in October 2017.

TROPOMI has a push-broom design with a 2-D detector, which measures back-scattered radiation from the Earth's atmosphere for viewing zenith angles up to 57°, in the spectral region from UV to shortwave infrared. The instrument is equipped with a polarization scrambler, simplifying the radiative transfer analysis. The width of the TROPOMI swath is about 2600 km, which results in daily (near-)global coverage with about 25 million measurement points. In band 4, where NO₂ is retrieved, TROPOMI provides 450 measurements across-track, with a minimal width of 3.5 km.

The design of OMI is similar to that of TROPOMI, but OMI measures in a smaller spectral range (270–500 nm) (Levelt et al., 2006, 2018). Another important difference is that OMI has only 60 across-track measurements, with the smallest pixels having a width of 25 km. Along track, the resolution of TROPOMI is 7 km (5.5 km since August 2019), compared to 13 km for OMI. Combined, the area of the smallest TROPOMI pixel is 19 km², while it is 325 km² for OMI, a factor of 17 improvement in spatial resolution. Both instruments are in a sun-synchronous ascending orbit and have an Equator overpass time of about 13:30 local time.

To retrieve tropospheric NO₂ columns, TROPOMI uses a three-step retrieval approach based on the DOAS (differential optical absorption spectroscopy; Platt and Stutz, 2008) technique: first the slant column density (N_s) is retrieved by spectral fitting of a modeled reflectance spectrum to the observed reflectances in the 405–465 nm window (van Geffen et al., 2021b, 2020; Zara et al., 2018). In the second step, data assimilation in the global chemistry transport model 5 (TM5-MP) results in vertical NO₂ profiles that are then used to separate the stratospheric and tropospheric contribution to the slant columns (van Geffen et al., 2020; Dirksen et al., 2011). In the last step, air mass factors (AMFs) are calculated (Lorente et al., 2017) to translate the N_s into vertical column densities (N_v). The AMF is calculated using the DAK radiative transfer model (de Haan et al., 1987; Stammes, 2001) and accounts for the viewing and solar geometry, as well as surface properties and cloud effects. Cloud height information is retrieved with TROPOMI's FRESCO+ cloud algorithm (driven by the 761 and 765 nm O₂ absorption depths) and cloud fraction from the reflectance levels within the 405–465 nm NO₂ fitting window. Other input parameters to the TROPOMI AMF calculation are the surface albedo climatology (Kleipool et al., 2008; 0.5° × 0.5°), a priori NO₂ profiles simulated with TM5-MP (Williams et al., 2017; 1° × 1°), and terrain height from Global 3 km Digital Elevation Model (DEM_3KM).

The retrieval of tropospheric NO₂ columns ($N_{v,trop}$) from OMI (Boersma et al., 2018) proceeds along the same lines and is therefore similar in many aspects. On the other hand, especially spatial resolution, signal-to-noise, and the retrieval of cloud properties differ as highlighted in Table 1.

Clouds have several relevant effects on NO₂ retrieval. Clouds shield the lower part of the atmosphere which is most

influenced by anthropogenic emissions including those from shipping. Therefore, data users are typically advised to consider scenes with cloud radiance fractions below 50 % (Eskes et al., 2019). Initial validation of TROPOMI NO₂ v1.2–1.3 pointed out that the FRESCO+ algorithm retrieves cloud heights close to the surface heights, leading to overestimations in the TROPOMI NO₂ AMFs and, consequently, underestimations of the tropospheric NO₂ columns (Verhoelst et al., 2021). Accurate knowledge of cloud fraction and height is key for high-quality trace gas column retrievals (e.g., Boersma et al., 2004; van Geffen et al., 2021a). A detailed description of the TROPOMI and OMI cloud algorithms and recent updates therein is given in the following subsection.

2.2 Improved TROPOMI FRESCO+, OMI, and VIIRS cloud retrievals

FRESCO+ (Fast Retrieval Scheme for Clouds from the Oxygen A band) retrieves cloud pressures from the relative depth of O₂-A band measurements (Koelemeijer et al., 2001; Wang et al., 2008) using three spectral windows at 758–759 nm (continuum, no absorption), 760–761 nm (strong absorption), and 765–766 nm (moderate absorption). In the algorithm, clouds are assumed to be Lambertian reflectors with a fixed albedo of 0.8, consistent with assumptions for the NO₂ AMF calculation. The surface albedo assumed in the cloud pressure retrieval is from the GOME-2 minimum Lambertian-equivalent reflectivity (LER) climatology at 758 and 772 nm (Tilstra et al., 2017), which is a potential source of uncertainty in the cloud pressure retrieval as the resolution and overpass time of GOME-2 are different from TROPOMI. FRESCO+ has been compared to other cloud data sets by Compennolle et al. (2021), who reported on tendencies in FRESCO+ to overestimate cloud pressures.

To address the high-bias in TROPOMI FRESCO+ cloud pressures, a new version of the FRESCO+ algorithm was introduced and implemented in the operational NO₂ retrieval with the introduction of TROPOMI v1.4 in December 2020. This version, called FRESCO+ wide, uses a wider spectral window for the cloud retrieval (765–770 nm, see Table 1), which includes the flank of the absorption band, where oxygen absorption is weaker than in the center of the O₂-A band (761 and 765 nm). Adding weaker O₂ absorption features improves the sensitivity to clouds low in the atmosphere. This is not possible from the strong O₂ absorption at 761 nm, which is so close to saturation that it becomes difficult to use its absorption depth in order to distinguish between bright reflecting layers at the Earth's surface and reflecting surfaces in the lower atmosphere.

Prior to the implementation of FRESCO+ wide in the operational TROPOMI NO₂ retrieval in December 2020, KNMI produced four periods with TROPOMI NO₂ test data based on FRESCO+ wide, the so-called diagnostic data set 2B (DDS-2B). DDS-2B contains data from four v1.2–v1.3

Table 1. Retrieval settings for the TROPOMI and OMI NO₂ retrievals used in this work.

		TROPOMI v1.2–1.3	TROPOMI v1.4–2.1*	OMI QA4ECV
Data availability		ESA science hub	ESA science hub	qa4ecv.eu
Public data period		30 Apr 2018–29 Nov 2020	29 Nov 2020–1 Jul 2021	Oct 2004–
Spatial resolution at nadir		3.5 km × 5.5 km	3.5 km × 5.5 km (3.5 km × 7 km)	13 km × 25 km
N_s	Fitting window	405–465 nm	405–465 nm	405–465 nm
	Signal-to-noise ratio	~ 1500	~ 1500	~ 500
	Solar reference spectrum	Daily	Daily	2005 average
	DOAS polynomial degree	5	5	4
	Intensity offset correction	No	No	Yes
	Destriping	Yes (since v1.2)	Yes	Yes
AMF	Surface albedo	OMI minimum LER at 440 nm (0.5°)	OMI minimum LER at 440 nm (0.5°)	OMI minimum LER at 440 nm (0.5°)
	A priori NO ₂ profiles	TM5-MP at 1° × 1°	TM5-MP at 1° × 1°	TM5-MP at 1° × 1°
	Cloud retrieval	FRESCO+	FRESCO+ wide	OMCLDO2
	Cloud fraction	Retrieved from 405–465 nm continuum	Retrieved from 405–465 nm continuum	Retrieved from 470–490 nm continuum
	Cloud pressure	Narrow O ₂ –A band (758, 761, and 765 nm)	Wide O ₂ –A band (758, 761 nm and 765–770 nm)	O ₂ –O ₂ absorption feature (477 nm)
	Surface albedo in cloud pressure retrieval	GOME-2 minimum LER at 758 and 772 nm (0.25° × 0.25°)	GOME-2 minimum LER at 758 and 772 nm (0.25° × 0.25°)	OMI minimum LER at 758 and 772 nm (0.5° × 0.5°)

* In addition to improved cloud parameters, TROPOMI v2.1 data has improved further through a better calibration of level-1 spectra, especially in the treatment of outliers and saturation (Ludewig et al., 2020), and through improvements in the NO₂ algorithm itself (van Geffen et al., 2021a). Version v2.1 is only used for production of the DDS-2B test data and not for publicly released data. Version v2.2, available publicly as of July 2021, is essentially the same as v2.1.

periods during 2018–2019 additionally processed with v2.1 of the TROPOMI algorithm. The most significant difference between the two is that v2.1 (and v1.4) uses cloud fractions and AMFs determined from the FRESCO+ wide cloud pressure instead of the FRESCO+ cloud pressures used in v1.2–v1.3 data.

Additionally, we use co-sampled cloud information from the Ozone Monitoring Instrument (OMI) on board of EOS-Aura. The OMI OMCLDO2 retrieval uses the relative depth of the O₂–O₂ absorption feature at 477 nm to retrieve cloud pressures (Acarreta et al., 2004; Veeffkind et al., 2016). The general approach of using Lambertian reflectors is similar to the FRESCO+ algorithm, but an important difference is that the OMCLDO2-algorithm needs to account for Raman scattering and O₃ absorption and that the absorption strength of the O₂–O₂ features is proportional to the square of the O₂ concentration, making it more sensitive to low clouds compared to FRESCO+.

We also use cloud information from VIIRS (Visible Infrared Imager Radiometer Suite) on board of the SUOMI

National Polar-orbiting Partnership (SNPP) as a completely independent means of verification. SNPP orbits the Earth in a sun-synchronous, ascending node with full daily global coverage and observes the same scenes as TROPOMI within 3 min. We use NASA's CLDPROP L2 VIIRS-SNPP cloud product (Platnick et al., 2017) with a resolution of 750 m at nadir, which provides a cloud mask, cloud (top) pressure, cloud optical thickness (COT), and cloud water phase for each pixel retrieved. The VIIRS retrieval derives a cloud top temperature using an optimal estimation approach in the thermal infrared spectral bands M14–M16 (8.5–12.3 μm). In a subsequent step, these cloud top temperatures are converted to cloud pressures using numerical weather prediction temperature profiles (Heidinger and Li, 2017). In addition to the cloud top pressure, we use the VIIRS cloud optical thickness (COT) to generate (effective) cloud fractions that can be compared directly to the TROPOMI cloud fractions. First, we derive a geometrical cloud fraction by calculating the share of cloudy VIIRS pixels per grid cell. Then, we translate this geometrical cloud fraction $f_{c,geo}$ into a effective cloud

fraction $f_{c,\text{eff}}$ using

$$f_{c,\text{eff}} = f_{c,\text{geo}} \cdot a_c / 0.8, \quad (1)$$

with a_c being the cloud albedo. The cloud albedo is calculated from the VIIRS COT and a previously established empirical relationship between cloud optical thickness and cloud albedo for liquid water clouds (Buriez, 2005; Boersma et al., 2016)¹.

To evaluate the improvements in the FRESKO+ wide retrieval, we compare daily gridded, co-sampled cloud data from (partly) cloudy pixels seen by TROPOMI (FRESKO+ and FRESKO+ wide), OMI, and VIIRS over parts of the Mediterranean Sea (37.0–41.25° N, 2.0–8.0° W), the Bay of Biscay (43.5–47.5° N, 10.0–3.0° E), and Northwest Europe (50.0–53.0° N, 4.0–9.0° W). These regions represent different surface types (land and ocean), climatological conditions, and pollution levels. We define partly cloudy pixels as all pixels with an effective cloud fraction $f_c \geq 0.05$. For TROPOMI we additionally apply sufficient quality of retrieval ($f_{QA} \geq 0.5$) and a pressure difference between surface pressure and cloud pressure of at least 7 hPa. The last filter is applied to filter out “ghost” clouds coming from sun glint viewing geometries (see Sect. 2.3 below). For OMI, we use the OMCLDO2 cloud properties and take only pixels with solar and viewing zenith angles smaller than 80° into account. As Eq. (1) is valid for liquid water clouds only, we select liquid water clouds and reject ice clouds, as indicated by the VIIRS cloud water phase. Around 25 %–30 % of VIIRS pixels are missed due to this filter.

2.3 Sun glint in the TROPOMI NO₂ retrieval

The term *sun glint* refers to particular satellite viewing geometries, under which the ocean acts as a mirror by reflecting sun light directly to the satellite instrument. In the TROPOMI data product pixels that are potentially in sun glint mode are identified based on the combination of their solar and viewing zenith and azimuth angles. The sun glint condition is fulfilled when the scattering angle Θ is smaller than a threshold angle Θ_{max} :

$$\Theta = \arccos[\cos\theta \cos\theta_0 - \sin\theta \sin\theta_0 \cos(\phi_0 - \phi)] \leq \Theta_{\text{max}}, \quad (2)$$

with θ and θ_0 being the solar and viewing zenith angles and ϕ and ϕ_0 the solar and viewing azimuth angles, respectively (see Fig. S1). For the TROPOMI data products the maximum threshold angle has been set at 30°. Smaller angles are used before, e.g., for SCIAMACHY and GOME-2 (Loots et al.,

2017). The TROPOMI algorithm treats the enhanced albedo as a partially cloudy scene with the cloud pressure located at or close to the sea surface.

2.4 Relationship between NO_x emissions and columns

When studying NO₂ columns to investigate emission trends, the non-linearity of NO_x chemistry needs to be taken into account. For example, the lifetime of NO_x depends on the background O₃ level, the available sun light, and NO_x concentrations themselves (Jacob, 1999). We use a (modeled) β factor to express the sensitivity of relative NO₂ column changes to changes in the relative emission strength following the approach in Vinken et al. (2014a) with

$$\beta = \frac{\Delta E/E}{\Delta N/N}, \quad (3)$$

where $\Delta E/E$ represents the imposed relative change in NO_x emission flux and $\Delta N/N$ the relative change in subsequently simulated tropospheric NO₂ columns. Here we use β values from Vinken et al. (2014b) modeled with GEOS-Chem at 0.5° × 0.67° and accounting for plume-in-grid chemistry. These β values have a similar spatial resolution as the spatially averaged TROPOMI NO₂ signals from ships (see Fig. 9). As we are interested in European seas only, we average β in the area 35–40° N and 5° E–10° W for Gibraltar and 30–37° N and 15–35° W for the Eastern Mediterranean. We use the resulting β value to estimate relative changes in NO_x emissions $(E_{2020} - E_{2019})/E_{2019}$ as

$$\frac{E_{2020} - E_{2019}}{E_{2019}} = \beta \cdot \frac{N_{\text{obs},2020} - N_{\text{obs},2019}}{N_{\text{obs},2019}}, \quad (4)$$

where $(N_{\text{obs},2020} - N_{\text{obs},2019})/N_{\text{obs},2019}$ is the observed relative change in NO₂ columns.

2.5 AIS data and ship-specific data

To relate the TROPOMI NO₂ columns to shipping activity, we use data from the automatic identification system (AIS) for shipping. Since 2005, the International Maritime Organization (IMO) requires all ships with a gross tonnage over 300 and all passenger ships to carry an AIS transponder. These transponders broadcast static (e.g., identity, size) and dynamic (e.g., position, speed, course) information of the ship, which can be received by other ships, shore stations, and satellites (International Maritime Organization (IMO), 2014). Here we use historical AIS data available to the Dutch Human Environment and Transport Inspectorate (ILT) to assess changes in shipping activity over densely traveled European shipping lanes in 2019 and 2020. We use AIS data of ships in a part of the shipping lane in the Eastern Mediterranean (31.91–34.53° N and 25.91–27.67° E) and close to the Strait of Gibraltar (35.0–37.0° N and 4.0–2.5° W). Furthermore, we use information on ship dimensions from the official ship registrations (<https://gisis.imo.org/Public/Default>).

¹The cloud albedo a_c for liquid water clouds can be expressed as a 6th order polynomial of the VIIRS cloud optical thickness (τ) as $a_c = b_0 + b_1 \cdot \tau + b_2 \cdot \tau^2 + b_3 \cdot \tau^3 + b_4 \cdot \tau^4 + b_5 \cdot \tau^5 + b_6 \cdot \tau^6$ with the coefficients $b_0 = 0.0153$, $b_1 = 0.0967$, $b_2 = -0.00605$, $b_3 = 0.000212$, $b_4 = -0.00000405$, $b_5 = 0.000000392$, and $b_6 = -0.00000000150$.

aspx, last access: 20 December 2021) to calculate a ship emission proxy E from ship length L and ship speed v as $E \propto L^2 \cdot v^3$, as used, for example, in Georgoulias et al. (2020). For the areas and times under study, ship-specific data were available only for 50 % (Gibraltar) and 70 % (Eastern Mediterranean) of the ships.

3 Results

We start with demonstrating TROPOMI's capabilities to detect shipping NO₂ by applying established data selection criteria. Next, we show steps to optimize monitoring of ship emissions by making use of sun glint (Sect. 3.2) and recent improvements in the cloud retrieval (Sect. 3.3) and compare the improved TROPOMI data to OMI data in Sect. 3.4. We end with an application of our findings to quantify NO₂ emission reductions from shipping due to COVID in 2020 in Sect. 3.5.

3.1 Detection of NO₂ pollution over European shipping lanes

TROPOMI detects unprecedented spatial detail in shipping NO₂ over busy shipping routes. Figure 1 shows the summertime mean (May–September 2019) NO₂ columns from TROPOMI and OMI averaged to a common $0.0625^\circ \times 0.0625^\circ$ grid, as well as CAMS/STEAM NO₂ emissions (Granier et al., 2019; Johansson et al., 2017) for the same period. We find a clear signal of shipping NO₂ in the TROPOMI data west of Portugal and from the Strait of Gibraltar to the east. There are further indications of enhanced NO₂ related to shipping in the Bay of Biscay from the tip of Brittany towards the northwest of Spain, and in the Eastern Mediterranean from the south of Sicily towards the Suez Canal. Previous studies reported NO₂ enhancements over these shipping lanes with other satellites (e.g., by OMI; Vinken et al., 2014b). Additionally, we see a clear NO₂ enhancement in the Aegean Sea between Istanbul and the Greek islands, as well as around Denmark, as shown in Fig. 2, which to our knowledge have not been observed by satellite instruments previously. Furthermore, (clear) hints of shipping activity can be seen in the Baltic Sea, the eastern Aegean Sea, the Adrian Sea, northeast of Corsica, the British Channel, and several forks in the Eastern Mediterranean and southeast of Sicily, which are all present as shipping lanes in CAMS/STEAM emissions. Corresponding zoomed-in maps of TROPOMI tropospheric NO₂ and CAMS/STEAM emissions are shown in Appendix A. For the analysis, we selected mostly clear-sky pixels with a quality assurance value (f_{QA}) of 0.75 or higher as recommended in the TROPOMI (Eskes et al., 2019) and (equivalent settings) OMI user manuals (Boersma et al., 2017). These enhancements are not an artifact in the retrieval coming from the AMF calculation (see Sect. 2.1) as they are visible in tropospheric vertical column

densities $N_{\text{trop,geo}}$ using a geometric AMF (see Appendix B) shown in Fig. B1.

TROPOMI and OMI show a comparable high spatial correlation to CAMS/STEAM emission data of $R = 0.93$ and $R = 0.91$, respectively. For the calculation, we brought OMI and TROPOMI tropospheric data to the CAMS resolution ($0.1^\circ \times 0.1^\circ$) and selected only grid cells over the Mediterranean Sea. This was done to ensure comparable meteorological and chemical conditions. Next, we binned the data by emission strength in bins of $0.05 \times 10^{-10} \text{ kg m}^{-2} \text{ s}^{-1}$. A reduced major axis regression of all bins with more than 10 entries leads to the correlation coefficients given above. Corresponding scatter plots can be found in Fig. C1. The y-axis intercept of $1.07 (1.05) \times 10^{15} \text{ molec. cm}^{-2}$ for TROPOMI (OMI) represents the mean background NO₂ column over the summertime Mediterranean. Other emission bin sizes lead to slightly different but comparable regression results.

Besides the higher resolution of the TROPOMI instrument, TROPOMI $N_{v,\text{trop}}$ thus has a comparable spatial correlation with emission inventories when compared to OMI's. The distinct shipping lanes visible in Figs. 1 and B1 visualize TROPOMI's unprecedented capabilities to detect shipping NO₂.

3.2 Sun glint

For situations of sun glint (see Sect. 2.3) the usually dark ocean appears bright in the TROPOMI data, leading to a strong increase in the effective scene albedo with decreasing scattering angle as shown in Fig. 3a. Figure 3b shows that the increase in scene albedo leads to substantially higher vertical sensitivities, as diagnosed by the averaging kernels (AKs) in the operational TROPOMI NO₂ product. The sensitivity increased most in the lowest vertical layer, where the kernel values are on average $\approx 60\%$ higher for sun glint compared to non-sun glint circumstances (0.44 vs. 0.28). Increased albedo generally enhances a satellite sensor's sensitivity to NO₂ concentrations in the lower atmosphere (e.g., Eskes and Boersma, 2003), and sun glint scenes have been tentatively used previously to attribute shipping plumes to individual ships in the Mediterranean Sea (Georgoulias et al., 2020).

The scene albedo and vertical sensitivity can be further increased by focusing on scenes with low–moderate wind speeds ($\approx 2 \text{ m s}^{-1}$) as wind-induced waves are expected to change the reflectivity. Fig. 4a shows the relationship between effective scene albedo and wind speed for scenes with small scattering angles $\Theta \leq 15^\circ$. For very low wind speeds the mean scene albedo is almost as small as for non-sun glint scenes and smaller than for all other wind speeds. For wind speeds between 1.5 and 2.0 m s^{-1} we find an effective scene albedo of almost 0.25, which is approximately double compared to the average for these scattering angles and more than 5 times as high as for non-sun glint scenes. For higher wind speeds the scene albedo decreases to around 0.10. In Fig. 4b the effect on the averaging kernel profile is shown. As ex-

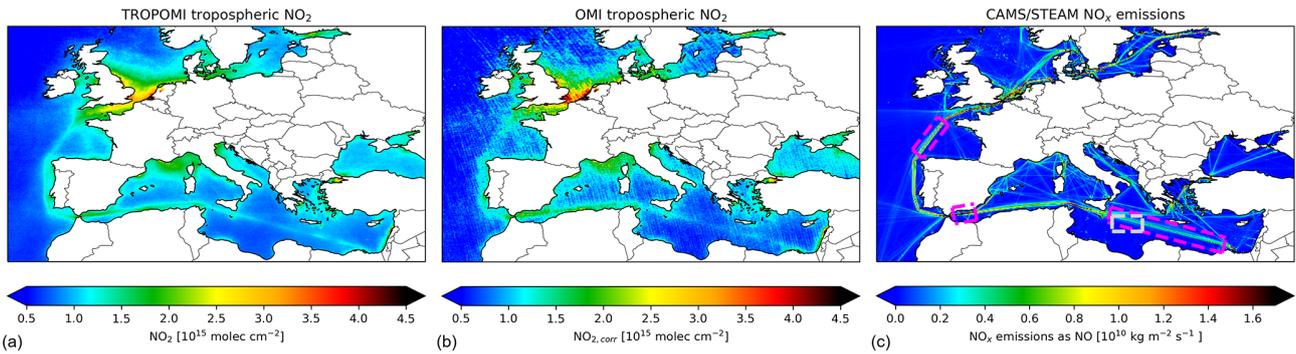


Figure 1. Summertime (May–September) mean tropospheric NO₂ columns from TROPOMI (a) and OMI (b) over European seas in 2019. Panel (c) shows the summertime mean NO_x emissions from the CAMS/STEAM emission inventory (Granier et al., 2019; Johansson et al., 2017). The gray and pink rectangles in the center panel indicate areas used in Sect. 3.2 and 3.4, respectively.

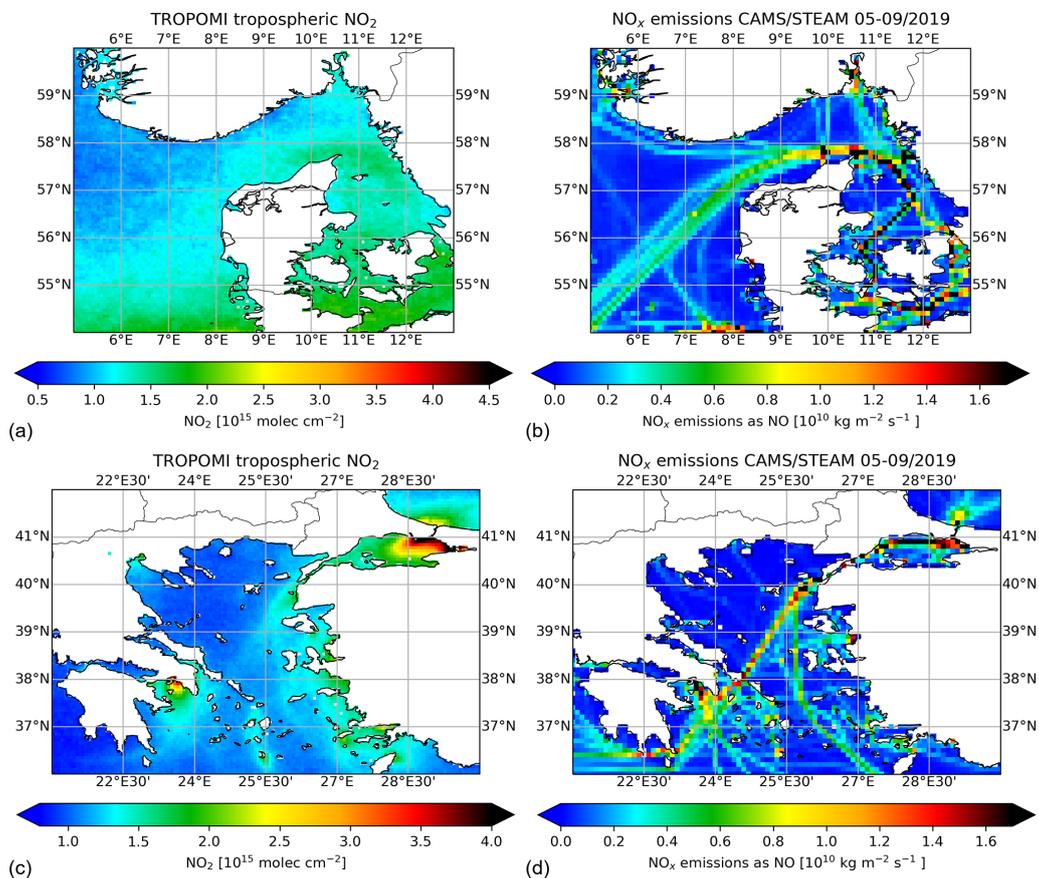


Figure 2. The 2019 summertime mean (May–September) tropospheric NO₂ columns from TROPOMI (a, c) and summertime mean NO_x emissions from the CAMS/STEAM emission inventory (b, d; Granier et al., 2019; Johansson et al., 2017) of shipping lanes around Denmark (a, b) and the eastern Aegean Sea (c, d) for the first time detected with satellites.

pected low wind speeds lead to the smallest AK in the lower atmosphere, whereas wind speeds between 1.5 and 2.0 m s⁻¹ show the largest AKs close to the sea surface. This relationship can be understood in terms of wind-induced sea surface roughness (Cox and Munk, 1956). Both very low and strong winds limit the probability that a scattering angle $\Theta \leq \Theta_{\max}$

leads to sun glint effects at the sensor: For very low wind speeds, the sea surface is effectively flat, leading to sun glint only for very small scattering angles $\Theta \ll \Theta_{\max}$, whereas for strong winds the sea surface is so rough that the sun light is reflected in all directions, making the reflections towards the satellite instrument unlikely.

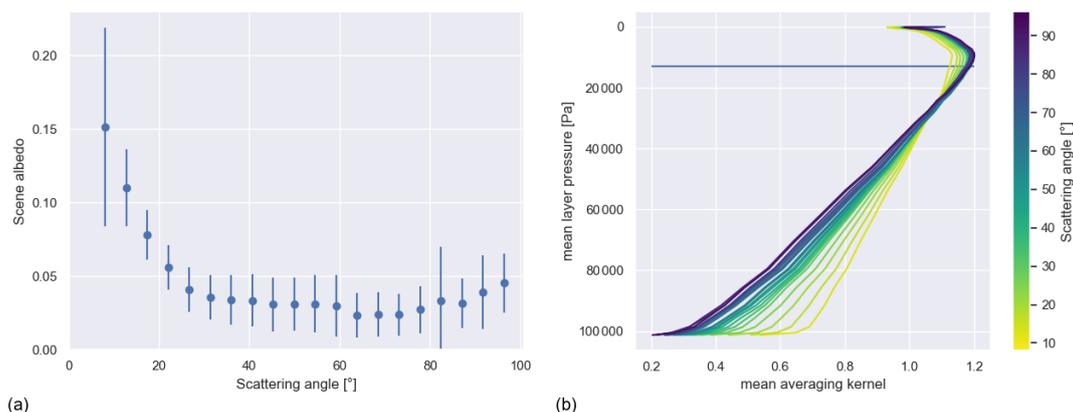


Figure 3. (a) Change in effective scene albedo with scattering angle over the Central Mediterranean north of Libya in June–July–August 2018 (see gray rectangle in Fig. 1c, $\approx 200\,000$ data points in total). The error bars indicate the standard deviation of each bin. (b) Mean averaging kernel (profiles) for different scattering angles, sampled as for (a). Only pixels with cloud radiance fractions < 0.25 or $p_{\text{surf}} - p_{\text{cloud}} \leq 300$ Pa were selected. The blue line in (b) indicates the average tropopause altitude.

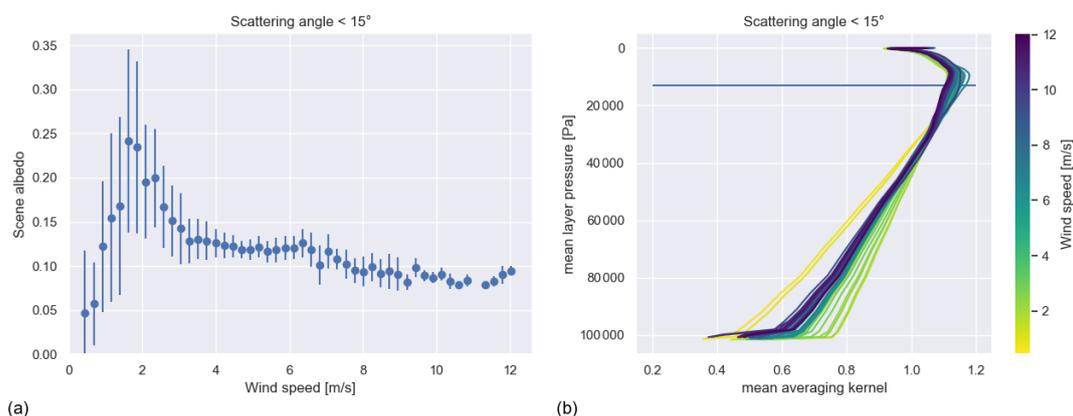


Figure 4. (a) Change in effective scene albedo with wind speed over the Central Mediterranean north of Libya in June–July–August 2018 (see gray rectangle in Fig. 1c) for scenes with scattering angles smaller than 15° ($\approx 22\,000$ data points in total). The error bars indicate the standard deviation of each bin. (b) Mean averaging kernel (profiles) for different wind speeds, sampled as for (a). Only pixels with cloud radiance fractions < 0.25 or $p_{\text{surf}} - p_{\text{cloud}} \leq 300$ Pa were selected. The horizontal blue line in (b) indicates the average tropopause altitude.

Additionally, we find that sun glint scenes can be used with confidence for detecting ship pollution signals from UV–Vis spectrometers such as TROPOMI, and the usage of sun glint data should be encouraged. The (normalized) tropospheric slant columns ($N_{\text{trop,geo}} = N_{\text{s,trop}}/M_{\text{geo}}$, see Appendix B) observed under sun glint conditions are 20%–25% higher than under non-sun glint conditions as shown in Fig. 5a. Vertical profiles of NO₂ over oceans typically feature enhancements from ships within the marine boundary layer and small background levels above (e.g., Chen et al., 2005b; Boersma et al., 2008; see Fig. 1). Therefore, it is no surprise that the AK increases in the lower atmosphere lead to small but detectable increases in (tropospheric) slant columns over the study region covering a frequently traveled shipping lane.

The enhanced slant columns are correctly accounted for by increased AKs leading to reliable retrievals under sun glint. Figure 5b compares the tropospheric vertical columns re-

ported in the official TROPOMI NO₂ product sampled under sun glint compared to non-sun glint conditions. The differences between the distributions are only small. Mean values for scene albedo, (normalized) tropospheric slant columns, and tropospheric vertical columns reported in the official TROPOMI NO₂ product for different scattering angles are summarized in Table 2.

3.3 Cloud properties

Here we evaluate TROPOMI’s capability to retrieve realistic cloud parameters retrieved from the 405–465 nm continuum reflectances and effective cloud pressures from the O₂–A band (Table 1), addressing recent improvements in the FRESKO+ algorithm to avoid overestimated cloud pressures (Compernelle et al., 2021). These improvements in

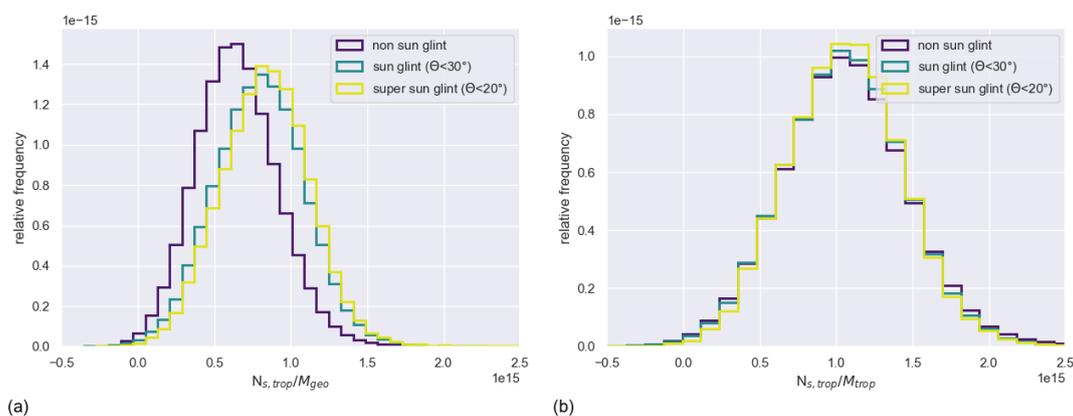


Figure 5. (a) Probability distribution of tropospheric NO₂ columns ($N_{s,trop}/M_{geo}$) over the Central Mediterranean north of Libya in June–July–August 2018 (see grey rectangle in Fig. 1c) taken under non-sun glint, sun glint ($\Theta \leq 30^\circ$), and super sun glint ($\Theta \leq 20^\circ$). (b) Probability distribution of tropospheric NO₂ columns in the official TROPOMI NO₂ product ($N_{s,trop}/M_{trop}$) for the same data selection.

Table 2. Summary of mean effective scene albedo, normalized tropospheric slant column, and $N_{v,trop}$ for non-sun glint, sun glint ($\Theta \leq 30^\circ$), and super sun glint ($\Theta \leq 20^\circ$) over the Central Mediterranean north of Libya in June–July–August 2018 (see gray rectangle in Fig. 1c).

	Non-sun glint	Sun glint	Super sun glint
Effective scene albedo	0.03 ± 0.02	0.08 ± 0.05	0.11 ± 0.05
$N_{trop,geo}$ (molec. cm ⁻²)	$(0.65 \pm 0.28) \times 10^{15}$	$(0.80 \pm 0.30) \times 10^{15}$	$(0.83 \pm 0.30) \times 10^{15}$
$N_{v,trop}$ (molec. cm ⁻²)	$(1.06 \pm 0.42) \times 10^{15}$	$(1.05 \pm 0.40) \times 10^{15}$	$(1.06 \pm 0.38) \times 10^{15}$

cloud retrievals lead to an inconsistency in the tropospheric NO₂ column record.

3.3.1 Cloud fractions

We find that improved TROPOMI cloud fractions are of sufficient quality to support the TROPOMI NO₂ AMF calculation. They show good correlation with independent data such as from OMI and VIIRS. TROPOMI v1.2 and v2.1 cloud fractions are very similar, with the new v2.1 cloud fractions being slightly smaller. More details can be found in Appendix D1.

3.3.2 Cloud pressure

FRESCO+ wide cloud pressures are a clear improvement over the FRESCO+ data used in v1.2–1.3. Figure 6 shows a comparison of gridded, co-sampled cloud pressure distributions from TROPOMI v1.2 (FRESCO+), TROPOMI v2.1 (FRESCO+ wide), OMI QA4ECV, and VIIRS over the Bay of Biscay between 1 and 7 July 2018. As expected, the improved TROPOMI v2.1 cloud pressures are ≈ 40 hPa lower than for v1.2, in line with their enhanced sensitivity, and show more realistic, elevated clouds. It is apparent that OMI cloud pressures are generally lower and show a flatter distribution than the other products. TROPOMI v2.1 and v1.2 show similar distributions as VIIRS, with v1.2 pressures higher by 50 hPa in the median and v2.1 moving closer to

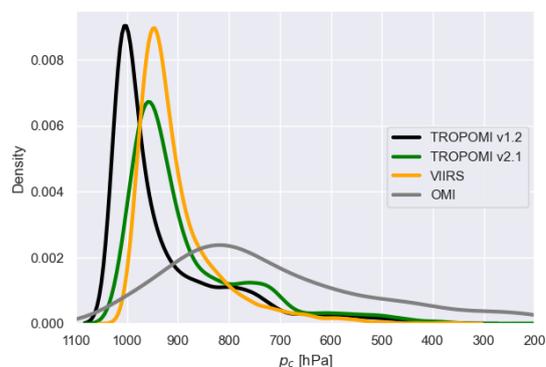


Figure 6. Probability distribution function of effective cloud pressures from TROPOMI v1.2, TROPOMI v2.1, OMI, and VIIRS for 1–6 July 2018 over the Bay of Biscay. Only cloud pressures for cloud fractions between 0.05 and 0.20 were selected as these are most relevant for AMF calculations for mostly clear-sky pixels.

VIIRS with a difference of 2 hPa relative to VIIRS. We find similar agreement between TROPOMI and independent data over the Mediterranean Sea and Northwest Europe as shown in Table D2. FRESCO+ wide cloud pressures agree best but remain higher than VIIRS in the median (both FRESCO cloud pressure distributions show a larger tail towards low pressures compared to VIIRS, possibly caused by filtering for liquid water clouds in VIIRS). This is in line with expectations as VIIRS's infrared cloud retrieval is mostly sensitive

Table 3. Evaluation of TROPOMI v2.1 cloud pressures against reference data for the Bay of Biscay.

	Median cloud pressure (hPa)	10th/90th percentile (hPa)	Geometric mean (hPa)
TROPOMI v1.2	979	753/1017	925
TROPOMI v2.1	930	717/988	884
OMI QA4ECV	769	426/934	720
VIIRS	928	794/973	901

to the cloud top (Platnick et al., 2017), whereas FRESCO's O₂-A band retrieval is more sensitive to the center of a cloud (e.g., Sneep et al., 2008). Around 25 %–30 % of VIIRS cloud retrievals in the areas studied here are ice water clouds and therefore not included in the analysis. As these clouds appear at higher altitudes, improved cloud pressures have only a little influence on the NO₂ columns (see Sect. 3.3.3).

3.3.3 Effect of improved cloud pressure on TROPOMI NO₂ columns

The improved cloud pressures lead to increases in NO₂ columns of up to 40 % depending on area and season. The left panels of Fig. 7 show the change in tropospheric NO₂ columns as a function of cloud pressure over the Bay of Biscay and Northwest Europe in summer. We see that NO₂ columns increase most for locations that had the highest original v1.2 cloud pressures and that the improvements are strongest when cloud pressures are reduced most (light blue dots). The increase over the Bay of Biscay is smaller (up to 0.1×10^{15} molec. cm⁻²) than over Northwest Europe (up to 1.0×10^{15} molec. cm⁻²), reflecting the higher pollution levels over the mainland. We see similar patterns with stronger improvements in winter, as shown in the right panels of Fig. 7. The increased v2.1 NO₂ columns indicate that the v1.2 TROPOMI NO₂ product suffers from a “cloud shielding” effect: NO₂ columns are underestimated due to clouds that are situated too low within the polluted boundary layer, and improved v2.1 cloud pressures (at least partly) resolve the low bias in v1.2 NO₂ columns. For this analysis, we compared the TROPOMI v2.1 columns retrieved with improved cloud information to the TROPOMI v1.2 NO₂ columns. We used 10 d in four different seasons (27 June–6 July 2018, 28 December 2018–5 January 2019, 25 March–5 April 2019, and 13–23 September 2019) for which both v2.1 test data and v1.2 operational data were available to us as part of the DDS-2B. Our comparison focused on mostly clear-sky situations ($f_c < 0.2$), which are most relevant for the detection of near-surface pollution sources.

We trained a deep neural network (DNN) to predict v2.1 columns for the full TROPOMI mission period up to December 2020 and thereby created a consistent data set. The

DNN-predicted v2.1 (hereafter v2.1p) reduces the mean difference to the retrieved v2.1 NO₂ columns to $< 0.01 \times 10^{15}$ molec. cm⁻² (original v2.1–v1.2 mean difference was 0.12×10^{15} molec. cm⁻²) over the three areas (see Sect. 2.2) of study during the four periods, suggesting considerable skill in the DNN approach. Details can be found in Appendix E.

Figure 8 shows the averaged NO₂ columns from v2.1p over the summer of 2019 and winter of 2019/2020. The difference map in the right panels indicates that predicted v2.1 NO₂ columns are higher by up to 0.5×10^{15} molec. cm⁻², especially over the most polluted seas such as the English Channel and shipping lanes. We find a stronger impact of the improved cloud pressures in the winter season, reflecting that NO₂ pollution is confined in a thinner marine boundary layer in that season.

3.4 Comparison of TROPOMI and OMI NO₂ columns in shipping lanes

TROPOMI detects a more pronounced and narrower region of ship NO₂ pollution than OMI. On average, TROPOMI v2.1p detects 45 % higher peak NO₂ values than OMI. TROPOMI data allow the attribution of 14 % more NO₂ to shipping lane enhancements and over 23 % to narrower shipping lanes. To quantitatively investigate TROPOMI's capability to detect NO₂ over shipping lanes under different measurement conditions and compare it to OMI's, we created average NO₂ cross sections over busy shipping lanes. We studied NO₂ enhancements in summer 2019 (June–August) over shipping lanes in the Bay of Biscay, from Sicily to the Suez Canal, and east of Gibraltar, the regions visually defined in Fig. 1c. First, we defined the location of the shipping lanes according to the emission data shown in Fig. 1c. Then, we calculated the average NO₂ columns along the shipping lane and parallel to it, taking care to exclude NO₂ columns measured over land. In that way we created an average cross section of NO₂ over shipping lanes. In the last step, we performed a background correction by subtracting a linear NO₂ background to isolate the NO₂ enhancements caused by shipping. The orbital data were gridded to regular grids of $0.0625^\circ \times 0.0625^\circ$ and $0.125^\circ \times 0.125^\circ$ resolution for TROPOMI and OMI, respectively. For TROPOMI only pixels with $f_{QA} > 0.75$ were taken into account. For OMI, a consistent filtering was applied, including maximal solar and viewing zenith angles of 80° and maximal cloud radiance fractions of 0.5. The resulting cross sections are shown in Fig. 9. Table 4 summarizes the peak value, the area under the curve (i.e., the total NO₂ attributed to shipping) and the full width at half maximum (FWHM) for the three shipping lanes. It should be noted that the grid used for OMI is 2 times coarser than the one used for TROPOMI. Gridding TROPOMI to the coarser grid used for OMI only changes the results slightly, indicating that the improved spatial resolution of TROPOMI indeed improves the detection of NO₂

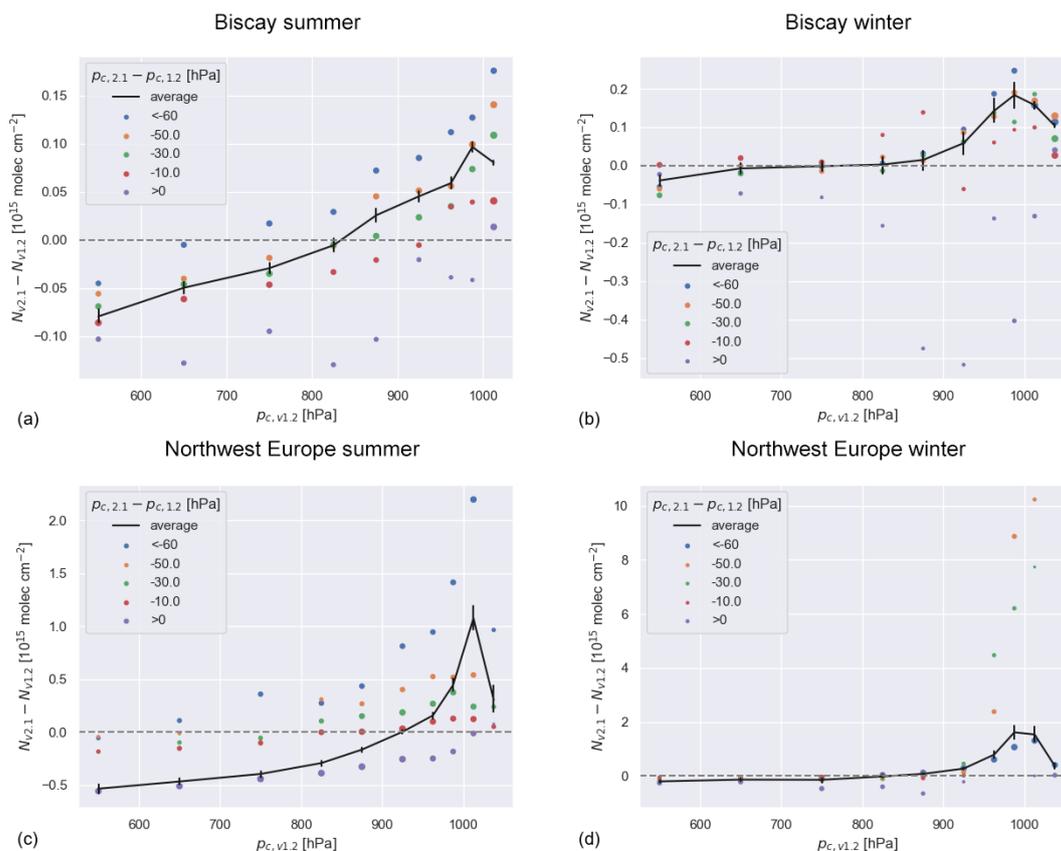


Figure 7. Difference between tropospheric NO₂ columns retrieved with TROPOMI v1.2 and v2.1 as a function of the v1.2 cloud pressure for 27 June–6 July 2018 over the mildly polluted Bay of Biscay in summer (a) and winter (b), as well as the highly polluted Northwest Europe (c, d). Colors indicate the difference in cloud pressures between the two versions. The marker size is proportional to the logarithm of the sample size, and the black line shows the effective average.

from narrow ship lanes and is in line with the finding of new shipping lanes shown in Fig. 2.

As already seen in Fig. 8, the v2.1p data set shows slightly higher NO₂ compared to the TROPOMI v1.2–v1.3 data, especially in the center of the lane, while background NO₂ is less affected by the correction. The impact of the DNN is larger in winter than in summer as discussed before.

For the Bay of Biscay it is also apparent that the NO₂ peak is shifted to the east for all data sets. As the location is defined by an emission inventory based on AIS data (and therefore real ship location), this is likely an effect of dominant westerly winds.

We conclude that TROPOMI provides a significant improvement for the detection of shipping NO₂ with sharper and more pronounced shipping lanes in seasonal averages. The improved v2.1p TROPOMI data increase the signal further.

3.5 Reductions in ship NO_x emissions during the COVID-19 pandemic

Emission proxies derived from AIS data and from TROPOMI NO₂ suggest emission reductions from shipping in 2020 compared to 2019 as depicted in Fig. 10c and f. While in the first 3 months of 2020 the ship emissions were generally higher compared to 2019, both emission proxies show reductions starting in April and lasting until the end of the year. This reduction can be linked to the COVID-19 pandemic, which led to economic lockdowns in many countries of the world. Europe had its most stringent measures in spring and autumn 2020.

We created daily $0.0625 \times 0.0625^\circ$ maps of TROPOMI data using v2.1p NO₂ columns as described in Sect. 3.3.3 with $f_{QA} \geq 0.75$. We calculate the area under the cross section as a measure for shipping NO₂ for monthly mean NO₂ columns for the shipping lanes of Gibraltar and the Mediterranean defined in Fig. 1c. Monthly TROPOMI shipping NO₂ for 2019 and 2020 can be seen in Fig. S2c. Figure 10d shows the relative change in shipping NO₂ from 2019 to 2020 in the Strait of Gibraltar. Using β values and the approach de-

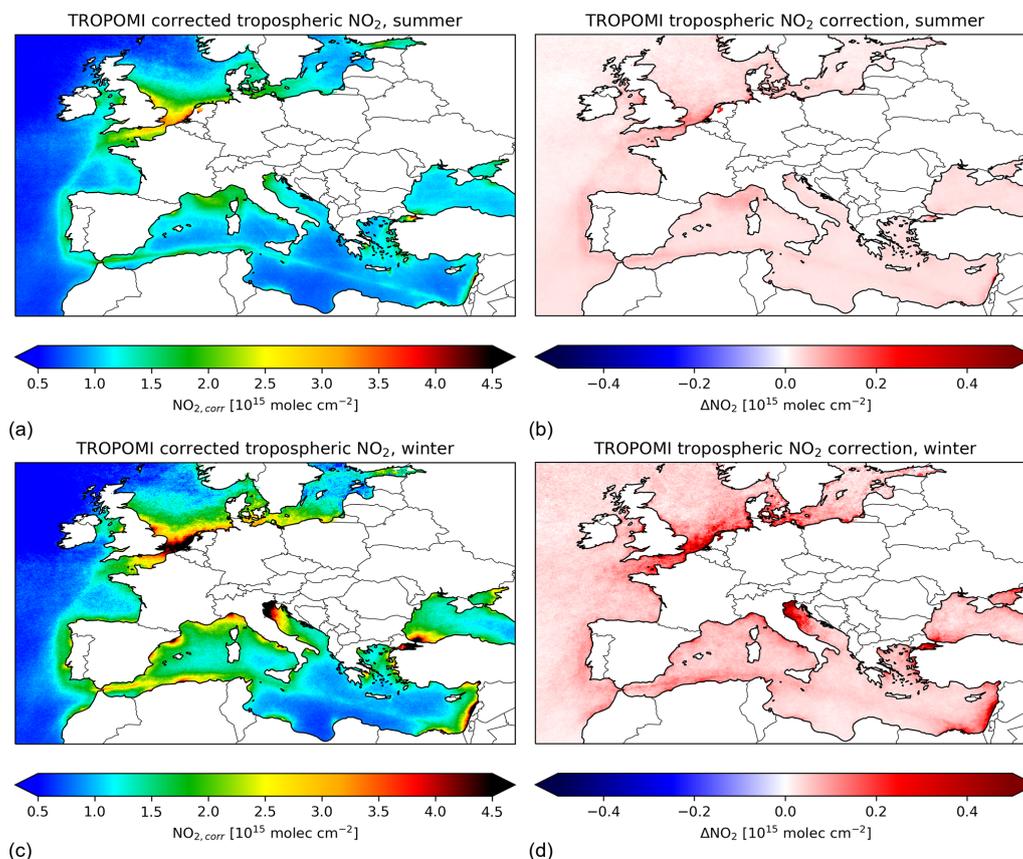


Figure 8. Effect of DNN correction: (a) corrected TROPOMI data for summer (May–September) 2019, (b) change in NO₂ columns by the correction for the same period (v2.1p–v1.3), (c) corrected TROPOMI data for winter (November–April) 2019/2020, and (d) change in NO₂ columns by the correction for the same period (v2.1p–v1.3). Land areas are whitened out for clarity.

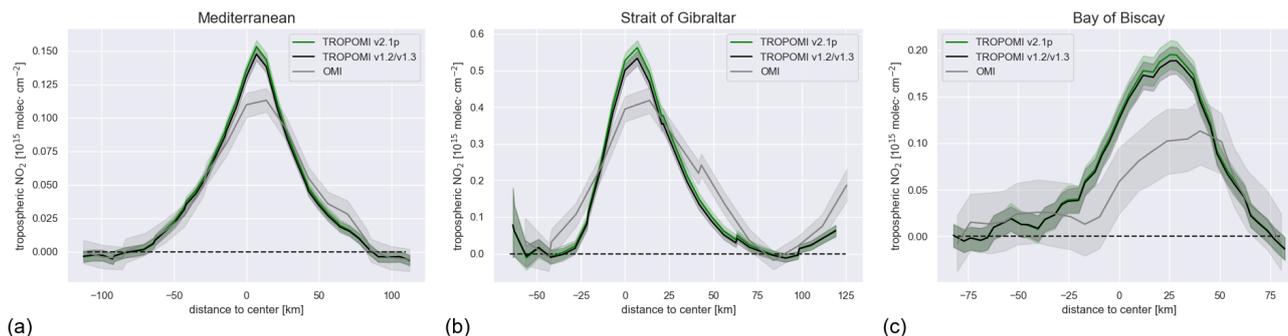


Figure 9. Mean enhancement cross sections in June–August 2019. TROPOMI v1.2–v1.3 in black, the improved TROPOMI v2.1p in green, and OMI in grey. Shaded areas indicate the 95% confidence interval.

scribed Sect. 2.4 and shown in Fig. 10e, we arrive at the TROPOMI-based relative change in emission changes shown in Fig. 10f.

The uncertainty in our top-down NO_x emission changes follows from the following: (i) the sensitivity of TROPOMI shipping NO₂ to the area of study ($\sigma_{\text{area}} = 5\%$), (ii) the inter-year differences on monthly averaged NO₂ columns over the areas of study caused by meteorology, and (iii) the combined

spatial and temporal spread of β as a result of differences in the chemical regime caused, for example, by differences in atmospheric composition and radiation ($\sigma_{\beta} = 0.15$). Figures 10d and F1d show σ_{area} , in panel (e) uncertainties (ii) and (iii) are used, while for panel (f) a full error propagation of all uncertainties listed above was performed. A full discussion on the uncertainty estimates can be found in Sect. S4.

Table 4. Statistics for the NO₂ enhancement cross section over the Mediterranean shipping lane.

Shipping lane	Product	Max (10 ¹⁵ molec. cm ⁻²)	Area under curve (10 ¹⁵ km molec. cm ⁻²)	FWHM (km)
Bay of Biscay	TROPOMI v1.2–v1.3	0.189	11.34	54.6
	TROPOMI v2.1p	0.195	11.72	54.6
	OMI	0.113	7.75	59.2
Strait of Gibraltar	TROPOMI v1.2–v1.3	0.534	24.47	41.3
	TROPOMI v2.1p	0.562	26.18	41.7
	OMI	0.418	28.83	63.8
Mediterranean	TROPOMI v1.2–v1.3	0.148	8.80	52.3
	TROPOMI v2.1p	0.153	9.19	52.6
	OMI	0.113	8.56	70.2

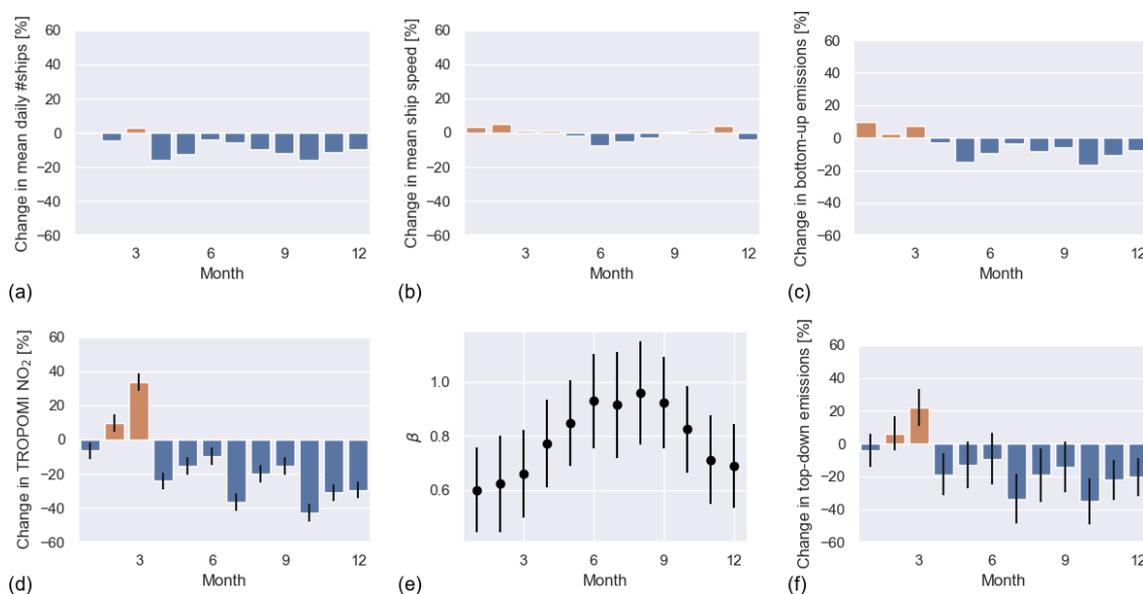


Figure 10. (a) Relative change in monthly mean of daily number of ships passing the Strait of Gibraltar between 2019 and 2020 inferred from AIS data. (b) Same but with average ship speed. (c) Relative change in emission proxy ($v^3 \cdot L^2$). (d) Relative change in TROPOMI shipping NO₂. (e) Monthly β values from Vinken et al. (2014b) with month-to-month variability imposed by monthly values from Verstraeten et al. (2015). Uncertainty intervals represent the temporal and spatial variability in β (see discussion in the text). (f) Relative change in top-down emissions from shipping. Error bars represent the propagated uncertainties in TROPOMI shipping NO₂, β , and differences in meteorological conditions between 2019 and 2020 (see discussion in the text).

Additionally, we used AIS data to calculate an AIS-based emission proxy as described in Sect. 2.5. We filtered for days with TROPOMI coverage of at least 50 % of each study area. AIS data indicate that the number of ships passing per month through the Strait of Gibraltar has reduced from March 2020 onwards relative to 2019 (Figs. 10a and S2a). The average speed of the ships passing through the shipping lanes is lower between May–September 2020 compared to the same period in 2019 as well (Figs. 10b and S2b). This is in agreement with a study by Millefiori et al. (2020) who found an increase in container ship speed in May and June in 2019 which is absent in 2020 leading to a relative decrease. Finally, Fig. 10c shows the relative change in AIS-deduced emission proxy

from 2019 to 2020. Similar results for the shipping lane in the Mediterranean can be found in Figs. F1 and S3.

Several studies report changes in ship activity in 2020 using AIS data. In addition to the 5 % decrease in ship speed in the Mediterranean between March and April 2020 compared to 2019 mentioned above, Millefiori et al. (2020) reported global mobility of container ships to have decreased by 10 % between March and June 2020 compared to the previous year. March et al. (2021) find increases in traffic density for January and February 2020 with decreases in March–June, with western Europe showing very strong reductions. Both studies show strong variations by vessel category and geographical distribution. Doumbia et al. (2021) find a global

decrease in container ship port calls in 2020 of 7 %, with a monthly local reduction of 20 % for Europe in June. The timing and magnitude of reductions reported in these studies agree with our findings: on average, AIS data indicate a reduction of 9 % (2 %) in April–December for Gibraltar (Mediterranean). The TROPOMI-based emission estimates agree in timing but show larger magnitude in reduction (20 % and 10 %) in April–December for the shipping lanes in the Strait of Gibraltar and the Eastern Mediterranean, respectively.

While the top-down emission reductions show a larger magnitude compared to the bottom-up emissions, they largely agree within the margin of uncertainty on a month-to-month basis. The difference in the mean reduction magnitude might be due to chemistry. The β values used here are calculated on a coarse grid ($0.5^\circ \times 0.67^\circ$). Additionally, we assume the chemical conditions in 2019 and 2020 to be similar to 2006 for when the β values were calculated. Furthermore, lateral transport complicates the choice of NO₂ background as a discrimination between land and ship emissions is not possible. The NO₂ background in turn has a large influence on the top-down emission estimate. These factors are all considered in our uncertainty estimates of the top-down emission changes. Other possible sources of uncertainty lie in the different temporal and spatial sampling of AIS and TROPOMI data and the simplified emission proxy. However, this is not expected to lead to a systematic bias.

4 Discussion and conclusion

We used tropospheric NO₂ column observations from the TROPOMI sensor to optimally monitor ship NO₂ pollution and study the changes in ship NO_x emissions over European seas in 2019–2020. Satellite observations of tropospheric NO₂ columns provide valuable information on ship air pollution over open seas, which can be used to inform compliance monitoring by flag states and national authorities. We evaluated the high-resolution TROPOMI NO₂ retrievals for its potential to better detect ship NO₂ pollution. In European waters alone, TROPOMI finds six new lanes with enhanced NO₂ ranging from the Aegean Sea to the Skagerrak between Denmark and Norway, which are not detected by OMI and which have not previously been reported in the literature. These newly found lanes of pollution coincide with busy sailing routes and bottom-up emission proxies.

To better understand the recent detection of an individual ship's NO₂ plume under conditions of sun glint, we examined how sun glint viewing geometries affect subsequent steps in the TROPOMI retrieval procedure. We find that sun glint drives higher apparent scene reflectivity, which enhances the signal strength from spectral fitting of NO₂ columns along the average light path by 20 %–30 % over clear-sky shipping lanes. In such situations, the vertical sensitivity to NO₂ within the marine boundary layer increases by

up to 60 %. This effect is especially strong when sea surface wind speeds are low but non-zero. When winds are strong, the wash causes sunlight to be reflected in other directions than directly towards the satellite, leading to little gain in vertical sensitivity. We find that the TROPOMI NO₂ algorithm accounts for these effects so that data within and outside of sun glint geometries can be used with confidence. Nevertheless, our work clearly indicates that optimal spectral fitting can be accomplished for small scattering angles ($< 15^\circ$) and sea surface wind speeds of $1.5\text{--}3\text{ m s}^{-1}$. Although selecting a subset fulfilling these sampling criteria reduces the amount of available data sharply, our findings indicate that sun glint conditions are beneficial for quantifying previously undetectable small NO_x emission sources over open sea and holding promise for also detecting other trace gases with UV–Vis satellite instruments over water, where surface reflectivity and vertical sensitivity are generally small.

In November 2020, KNMI implemented an improved FRESKO+ cloud retrieval called FRESKO+ wide in the operational TROPOMI NO₂ algorithm. We find here that this new FRESKO+ wide cloud retrieval provides some 50 hPa lower cloud pressures which agree better with coinciding cloud top heights from the VIIRS sensor than the standard FRESKO+. We show that the improved cloud pressures lead to a more realistic description of vertical sensitivities in the TROPOMI NO₂ algorithm and at least partly address the known low bias in the tropospheric NO₂ product prior to November 2020, thus not only solving a known issue in the TROPOMI NO₂ retrieval but also increasing signal strength. We then trained a neural network on a limited data set of simultaneously available standard and improved cloud and NO₂ retrievals. Based on four different training sets, the neural network learned the statistical relationship between standard FRESKO+ cloud pressures and other parameters and the new tropospheric NO₂ columns. We used the neural network to predict updated NO₂ columns for the entire 2019–2020 TROPOMI NO₂ record. The neural network predicts a general increase in tropospheric NO₂ columns. Increases are particularly strong (up to $4 \times 10^{15}\text{ molec. cm}^{-2}$) in the most polluted regions of Europe in wintertime. Our predicted (v2.1p) TROPOMI data set enables the consistent analysis of temporal changes in NO₂ during the COVID year 2020 and is useful to other data users until the TROPOMI NO₂ reprocessing scheduled for 2022 has been completed.

We compared changes in our v2.1p TROPOMI NO₂ columns between 2019 and 2020 to changes in the number of ships, their speed, and their size obtained from AIS data in the main European traffic lanes. From April 2020 onwards, TROPOMI observes 25 % less NO₂ pollution than in the year before, in step with a 10 % reduction in the number of ships and a 5 % speed reduction relative to 2019. Accounting for non-linearity in local NO_x chemistry, we infer an average 20 % reduction in top-down NO_x emissions in the Strait of Gibraltar from ships during months in which COVID measures were in force in Europe, and global mobility decreased

as a result of the pandemic. For future research, a full chemical transport modeling of AIS-based emissions and strict co-sampling of AIS and TROPOMI data can help with understanding the observed differences in top-down and bottom-up emission changes and reduce the error margins.

We showed that TROPOMI is a superior instrument to analyze relatively small enhancements in NO₂ pollution over dark European seas. Its vertical sensitivity to ship pollution is substantially enhanced for small scattering angles under cloud free conditions and low wind speeds. Such sun glint scenes should allow improved detection of other pollutants, such as formaldehyde and SO₂ as well. KNMI's operational TROPOMI NO₂ product is subject to continuous improvement, which causes step changes in the publicly available data record until the official reprocessing has been finalized. Our improved (v2.1p) TROPOMI data set offers a consistent alternative that can be used over Europe in and after 2019 and may be applied to other regions of the world where consistent NO₂ time series are needed.

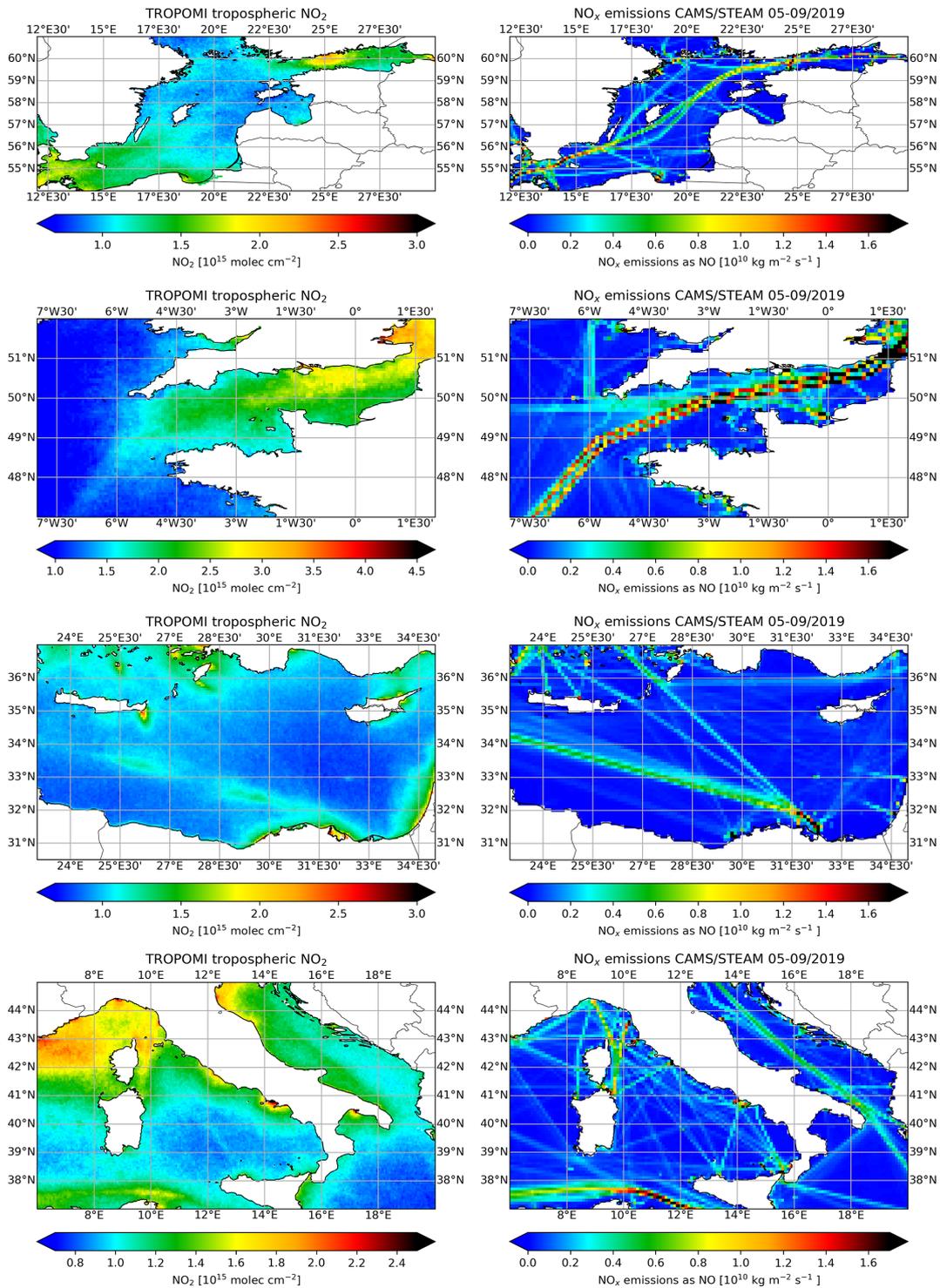
Appendix A: Zoomed-in NO₂ maps

Figure A1. Summertime mean (May–September) tropospheric NO₂ columns from TROPOMI (left panels) and summertime mean NO_x emissions from the CAMS/STEAM emission inventory (right panels; Granier et al., 2019; Johansson et al., 2017).

Appendix B: $N_{\text{TROP,geo}}$

We calculate a geometric tropospheric vertical column density $N_{\text{TROP,geo}}$ using

$$N_{\text{TROP,geo}} = N_{\text{s,trop}}/M_{\text{geo}}, \quad (\text{B1})$$

where $N_{\text{s,trop}}$ is the tropospheric slant column density which can be calculated from the TROPOMI files using

$$N_{\text{s,trop}} = N_{\text{s,tot}} - N_{\text{s,strat}} = N_{\text{s,tot}} - N_{\text{v,strat}} \cdot M_{\text{strat}}, \quad (\text{B2})$$

where M , N_{s} , and N_{v} are mean air mass factor, slant column density, and vertical column density, respectively. The subscripts trop, tot, and strat indicate tropospheric, total, and stratospheric columns, respectively. M_{geo} can be calculated using the solar zenith angle θ and the viewing zenith angle θ_0 as $M_{\text{geo}} = 1/\cos(\theta) + 1/\cos(\theta_0)$. The resulting tropospheric column is shown in Fig. B1.

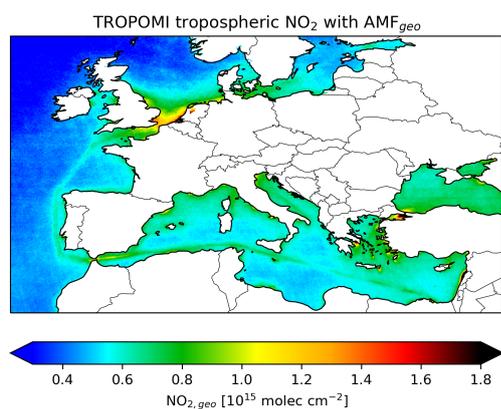


Figure B1. Mean of NO₂ columns calculated with geometrical AMF for summer 2019 (May–September); land areas have been whitened for clarity.

Appendix C: Spatial correlation to emissions

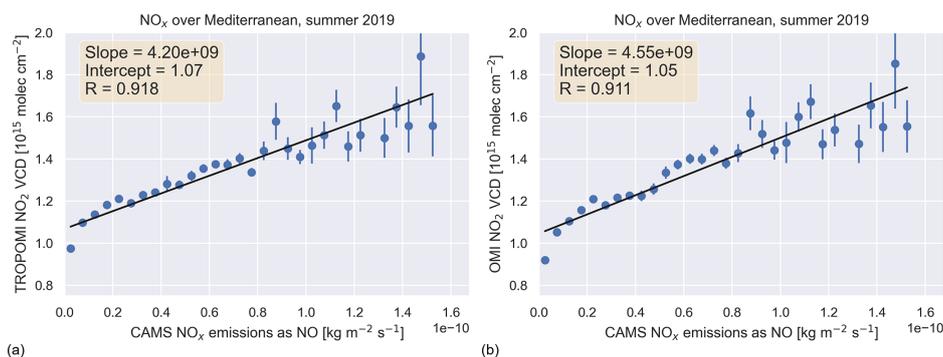


Figure C1. Scatter of binned summertime (May–September) 2019 tropospheric NO₂ columns vs. emissions from CAMS/STEAM for the same period at 0.1° × 0.1° in the Mediterranean. Error bars indicate the standard error of the bin. (a): TROPOMI; (b): OMI.

Appendix D: Cloud properties

Table D1. Evaluation of TROPOMI v2.1 cloud fractions over European shipping lanes (1–6 July 2018) against reference data.

Shipping lane		Mean bias	RMS	R^2	Regression
Biscay	TROPOMI v2.1 vs. 1.2	−0.020	0.036	0.99	$0.95 \cdot x$
	TROPOMI v2.1 vs. OMI QA4ECV	0.002	0.124	0.78	$0.01 + 0.97 \cdot x$
	TROPOMI v2.1 vs. VIIRS	−0.062	0.181	0.66	$-0.01 + 0.89 \cdot x$
Mediterranean	TROPOMI v2.1 vs. 1.2	−0.009	0.017	0.99	$0.96 \cdot x$
	TROPOMI v2.1 vs. OMI QA4ECV	0.00005	0.09	0.67	$-0.011.05 \cdot x$
	TROPOMI v2.1 vs. VIIRS	−0.050	0.147	0.60	$0.02 + 0.65 \cdot x$
NW Europe	TROPOMI v2.1 vs. 1.2	−0.015	0.046	0.95	$0.94 \cdot x$
	TROPOMI v2.1 vs. OMI QA4ECV	−0.038	0.111	0.76	$-0.01 + 0.91 \cdot x$
	TROPOMI v2.1 vs. VIIRS	−0.026	0.156	0.64	$0.04 + 0.74 \cdot x$

D1 Cloud fractions

The improved (v2.1) and old (v1.2) cloud fractions have a strong correlation ($R^2 = 0.99$), but v2.1 cloud fractions are 5 % lower on average; see Table D1. The spatiotemporal correlation between TROPOMI v2.1 and the well-established OMI QA4ECV cloud fraction product is also very high ($R^2 = 0.78$), with TROPOMI v2.1 cloud fractions 3 % lower than OMI on average. TROPOMI v2.1 shows high correlation ($R^2 = 0.66$) and somewhat lower cloud fractions (−11 %) compared to the co-sampled effective VIIRS cloud fractions. TROPOMI cloud fractions are especially lower for partly cloud-covered scenes, possibly resulting from biased surface albedos assumed in the TROPOMI retrieval (from the GOME-2 climatology at 0.5° resolution, see Table 1). We find a similar high correlation and small differences between TROPOMI and independent data over the Mediterranean Sea and Northwest Europe as shown in Table D1.

D2 Cloud pressures**Table D2.** Evaluation of TROPOMI v2.1 cloud pressures against reference data for European shipping lanes.

Shipping lane	Product	Median cloud pressure (hPa)	10th/90th percentile (hPa)	Geometric mean (hPa)
Mediterranean	TROPOMI v1.2	980	684/1010	920
	TROPOMI v2.1	947	653/978	889
	OMI QA4ECV	781	509/903	739
	VIIRS	935	743/976	896
NW Europe	TROPOMI v1.2	839	504/969	785
	TROPOMI v2.1	861	590/955	812
	OMI QA4ECV	740	474/862	712
	VIIRS	863	702/993	853

Appendix E: DNN

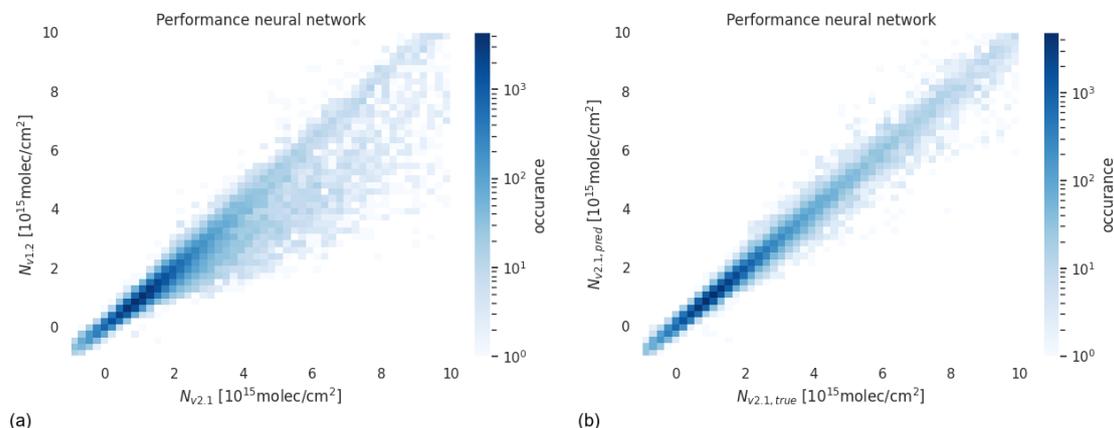


Figure E1. (a) Scatterplot of TROPOMI v1.2 (uncorrected) vs. actually retrieved v2.1 TROPOMI NO₂ columns observed over Europe in the four test periods. (b) Scatterplot of DNN-predicted vs. actually retrieved v2.1 TROPOMI NO₂ columns observed over Europe in all areas and periods under study.

An artificial neural network allows us to predict v2.1 columns for the full TROPOMI mission period up to December 2020. We find the predicted v2.1 columns to be close to actual retrieved v2.1 columns in a testing data set. Figure E1 illustrates the skill of the DNN approach to reliably predict v2.1 data: as a reduced major axis regression shows, the DNN-predicted v2.1 (hereafter v2.1p) NO₂ columns agree substantially better with the retrieved v2.1 NO₂ values ($N_{v2.1,true} = 0.98 \cdot N_{v2.1,pred} + 0.03 \times 10^{15} \text{ molec. cm}^{-2}$, $R^2 = 0.98$, $n = 56219$) compared to the originally retrieved v1.2 NO₂ columns ($N_{v2.1} = 0.87 \cdot N_{v1.2} + 0.09 \times 10^{15} \text{ molec. cm}^{-2}$, $R^2 = 0.91$). The improvement from TROPOMI v1.2 to v2.1 is driven by the improved cloud pressures and associated changes in the tropospheric AMFs.

We trained the artificial DNN using the Python package Keras (Chollet and others, 2015) with three hidden layers. We divided the combined v1.2 and v2.1 data sets in three random subsets for training (60%), validation (20%), and testing (20%). The input parameters to predict TROPOMI (pseudo) v2.1 NO₂ columns are $N_{v,v1.2}$, M_{trop} , f_{cl} , p_{cl} , all viewing geometry parameters, surface albedo, and the f_{QA} value (all from v1.2). The DNN was then trained to minimize the mean absolute difference between the predicted and actually retrieved v2.1 NO₂ columns from the training set. This means our prediction does not use FRESKO+ wide cloud pressures for dates outside the training set period. Rather, the DNN has been trained to predict new NO₂ columns based on the old FRESKO+ cloud pressures and other parameters. Our DNN application succeeds in reducing the mean difference between the predicted and retrieved v2.1 NO₂ columns to $< 0.01 \times 10^{15} \text{ molec. cm}^{-2}$ (original v2.1–v1.2 mean difference was $0.12 \times 10^{15} \text{ molec. cm}^{-2}$) over the three areas of study during the four periods, suggesting considerable skill in the DNN approach. Our improved data set consists of the original L2 TROPOMI NetCDF files with the predicted change in tropospheric NO₂ columns as additional variable.

To show that DNN is capable of capturing seasonal variations in NO₂ corrections and, more broadly, that we can use a generic DNN to correct historic TROPOMI v1.2 data, we train a DNN based on three seasons (summer, winter, and spring) and tested its predicted NO₂ columns against actually retrieved v2.1 data in autumn. This analysis is done for the three testing areas defined in Sect. 3.3. After application of DNN, the mean discrepancy between predicted and retrieved v2.1 NO₂ columns reduces to $< 0.01 \times 10^{15} \text{ molec. cm}^{-2}$ (original mean discrepancy: $0.09 \times 10^{15} \text{ molec. cm}^{-2}$), and R^2 improved from 0.82 to 0.97.

Appendix F: Ship NO_x emission reductions during the COVID-19 pandemic

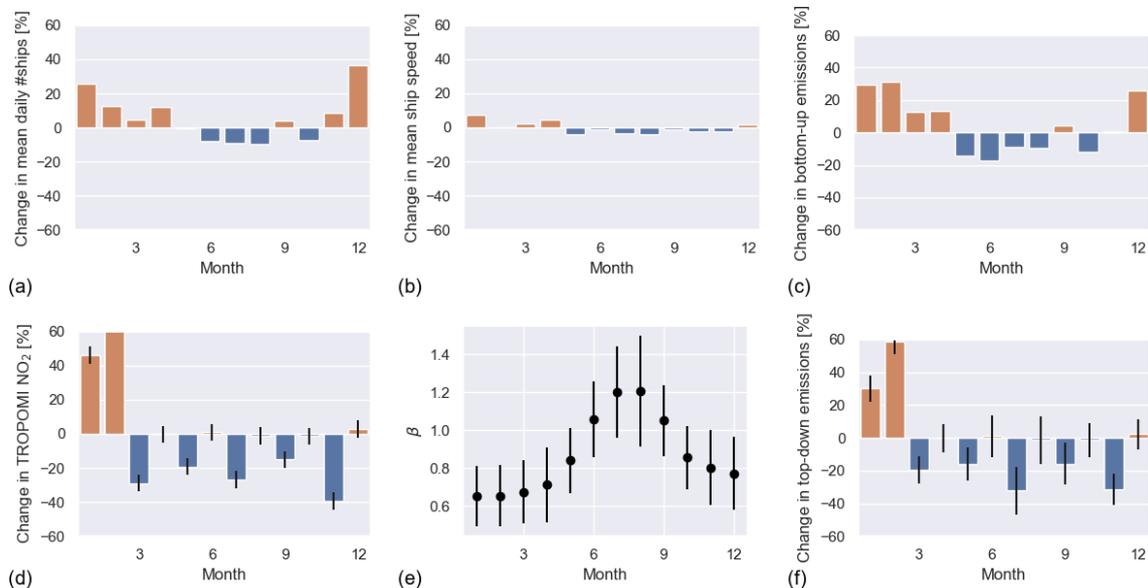


Figure F1. (a) Relative change in monthly mean of daily number of ships passing the Mediterranean shipping lane between 2019 and 2020. (b) Same but with average ship speed. (c) Relative change in emission proxy ($v^3 \cdot L^2$). (d) Relative change in TROPOMI shipping NO₂; the error bars indicate the sensitivity to changes in the area of study. (e) Monthly β values as discussed in Sect. 2.4. Error bars represent uncertainty originating from the temporal and spatial variability (see discussion in the text). (f) Relative change in top-down emissions from shipping. Error bars represent the propagated uncertainties in TROPOMI shipping NO₂, β , and differences in meteorological conditions between 2019 and 2020 (see discussion in the text).

Data availability. The data can be made available upon request by contacting the author (christoph.riess@wur.nl). TROPOMI L2 NO₂ is publicly available via the Copernicus open-access hub (<https://s5phub.copernicus.eu/dhus/#/home>, van Geffen et al., 2019).

Supplement. The supplement related to this article is available online at: <https://doi.org/10.5194/amt-15-1415-2022-supplement>.

Author contributions. TCVWR, KFB, and JvV designed the study. TCVWR performed the data analysis with support from KFB, JvV, and WP. TCVWR wrote the manuscript with contributions from KFB, JvV, and WP. JvV made the AIS data available. MS developed the FRESCO+ wide algorithm, and JvG provided specifics on the TROPOMI NO₂ data versions and made the DDS-2B available. HE oversees the NO₂ retrieval improvements at KNMI. All authors reviewed the manuscript.

Competing interests. The contact author has declared that neither they nor their co-authors have any competing interests.

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