

# A Mixed Sampling Approach for Temporal Trends of Spatial Means

Dick Brus<sup>1</sup>, Jaap de Gruijter<sup>1</sup>

<sup>1</sup>Alterra, Wageningen University and Research Centre



# Outline

Motivation and aim

Four statistical approaches in space–time

$D_S M_T$  approach

Estimation of Trend and its Variance

Case study

Conclusions

# Outline

Motivation and aim

Four statistical approaches in space–time

$D_S M_T$  approach

Estimation of Trend and its Variance

Case study

Conclusions

# Outline

Motivation and aim

Four statistical approaches in space–time

$D_{ST}$  approach

Estimation of Trend and its Variance

Case study

Conclusions

# Outline

Motivation and aim

Four statistical approaches in space–time

$D_{ST}$  approach

Estimation of Trend and its Variance

Case study

Conclusions

# Outline

Motivation and aim

Four statistical approaches in space–time

$D_{ST}$  approach

Estimation of Trend and its Variance

Case study

Conclusions

# Outline

Motivation and aim

Four statistical approaches in space–time

$D_{ST}$  approach

Estimation of Trend and its Variance

Case study

Conclusions

# Outline

Motivation and aim

Four statistical approaches in space–time

$D_S M_T$  approach

Estimation of Trend and its Variance

Case study

Conclusions



# Monitoring in Europe

- ▶ Water Framework Directive
- ▶ European Soil Strategy
- ▶ Habitats Directive
- ▶ Kyoto-agreement

# Monitoring in Europe

- ▶ Water Framework Directive
- ▶ European Soil Strategy
- ▶ Habitats Directive
- ▶ Kyoto-agreement

# Monitoring in Europe

- ▶ Water Framework Directive
- ▶ European Soil Strategy
- ▶ Habitats Directive
- ▶ Kyoto-agreement

# Monitoring in Europe

- ▶ Water Framework Directive
- ▶ European Soil Strategy
- ▶ Habitats Directive
- ▶ Kyoto-agreement

# Aim of research

To work out a new statistical sampling approach for estimating

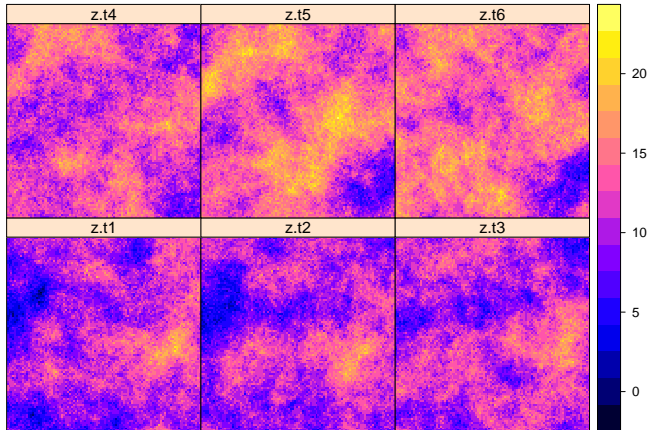
- ▶ temporal trends in an *area*,
- ▶ that can be used in situations where we can afford a *few sampling locations per sampling round* only, say less than 30

# Aim of research

To work out a new statistical sampling approach for estimating

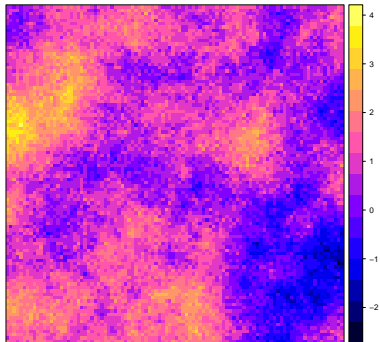
- ▶ temporal trends in an *area*,
- ▶ that can be used in situations where we can afford a *few sampling locations per sampling round* only, say less than 30

# Simulated Space-Time Field

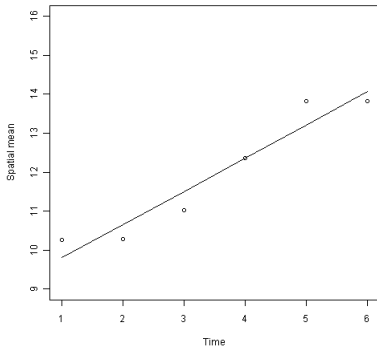


# Map of Trend versus Trend of Spatial Means

Map of Trend at Points



Trend of Spatial Means





# Outline

Motivation and aim

Four statistical approaches in space–time

$D_S M_T$  approach

Estimation of Trend and its Variance

Case study

Conclusions

# Design-based and model-based approach

## Definition of design-based and model-based approach

Type of approach	Sampling unit selection	Statistical inference
Design-based	Probability sampling	Design-based
Model-based	No requirement (purposive)	Model-based

# Four statistical approaches in space–time

		<i>Space</i>	
	Statistical approach	Design-based	Model-based
<i>Time</i>	Design-based	$D_S D_T$	$M_S D_T$
	Model-based	$D_S M_T$	$M_S M_T$

# Remarks on four approaches

- ▶ Fully design-based approach, e.g. compliance monitoring of space–time mean (Brus and Knotters (2008), Water Resources Research **44**)
- ▶ Fully model-based approach. Ter Braak *et al* (2008) JABES **13** used **geostatistical space–time model** to compare space-time patterns for predicting the temporal trend of spatial means

# Remarks on four approaches

- ▶ Fully design-based approach, e.g. compliance monitoring of space–time mean (Brus and Knotters (2008), Water Resources Research **44**)
- ▶ Fully model-based approach. Ter Braak *et al* (2008) JABES **13** used **geostatistical space–time model** to compare space-time patterns for predicting the temporal trend of spatial means

# Outline

Motivation and aim

Four statistical approaches in space–time

**D<sub>S</sub>M<sub>T</sub> approach**

Estimation of Trend and its Variance

Case study

Conclusions

# D<sub>S</sub>M<sub>T</sub> approach

- ▶ Design-based approach in **space** followed by model-based approach in **time**
- ▶ Probability sampling in space at all sampling rounds; design-based estimation of spatial means and of sampling variances
- ▶ No requirements on selection of sampling times
- ▶ For estimating temporal trend, **purposive** selection of sampling times best option
- ▶ Constant interval, first round at the start, last round at the end of monitoring period

# D<sub>S</sub>M<sub>T</sub> approach

- ▶ Design-based approach in **space** followed by model-based approach in **time**
- ▶ **Probability sampling** in space at all sampling rounds; **design-based estimation** of spatial means and of sampling variances
- ▶ No requirements on selection of sampling times
- ▶ For estimating temporal trend, **purposive** selection of sampling times best option
- ▶ Constant interval, first round at the start, last round at the end of monitoring period



# D<sub>S</sub>M<sub>T</sub> approach

- ▶ Design-based approach in **space** followed by model-based approach in **time**
- ▶ **Probability sampling** in space at all sampling rounds; **design-based estimation** of spatial means and of sampling variances
- ▶ No requirements on selection of sampling times
- ▶ For estimating temporal trend, **purposive** selection of sampling times best option
- ▶ Constant interval, first round at the start, last round at the end of monitoring period

# D<sub>S</sub>M<sub>T</sub> approach

- ▶ Design-based approach in **space** followed by model-based approach in **time**
- ▶ **Probability sampling** in space at all sampling rounds; **design-based estimation** of spatial means and of sampling variances
- ▶ No requirements on selection of sampling times
- ▶ For estimating temporal trend, **purposive** selection of sampling times best option
- ▶ Constant interval, first round at the start, last round at the end of monitoring period

# D<sub>S</sub>M<sub>T</sub> approach

- ▶ Design-based approach in **space** followed by model-based approach in **time**
- ▶ **Probability sampling** in space at all sampling rounds; **design-based estimation** of spatial means and of sampling variances
- ▶ No requirements on selection of sampling times
- ▶ For estimating temporal trend, **purposive** selection of sampling times best option
- ▶ Constant interval, first round at the start, last round at the end of monitoring period

# D<sub>S</sub>M<sub>T</sub> approach

- ▶ In estimating the trend a stochastic time-series model for the spatial means is used, i.e. **model-based estimation**
- ▶ Space–time field is a realisation of a stochastic space–time process
- ▶ Space–time process is only **partly** described by a model of the temporal variation of the spatial mean
- ▶ Uncertainty about trend accounts for
  - random selection of sampling locations
  - stochastic space–time process

# D<sub>S</sub>M<sub>T</sub> approach

- ▶ In estimating the trend a stochastic time-series model for the spatial means is used, i.e. **model-based estimation**
- ▶ Space–time field is a realisation of a stochastic space–time process
- ▶ Space–time process is only **partly** described by a model of the temporal variation of the spatial mean
- ▶ Uncertainty about trend accounts for
  - random selection of sampling locations
  - stochastic space–time process

# D<sub>S</sub>M<sub>T</sub> approach

- ▶ In estimating the trend a stochastic time-series model for the spatial means is used, i.e. **model-based estimation**
- ▶ Space–time field is a realisation of a stochastic space–time process
- ▶ Space–time process is only **partly** described by a model of the temporal variation of the spatial mean
- ▶ Uncertainty about trend accounts for  
– the random selection of sampling locations  
– the stochastic space–time process

# D<sub>S</sub>M<sub>T</sub> approach

- ▶ In estimating the trend a stochastic time-series model for the spatial means is used, i.e. **model-based estimation**
- ▶ Space–time field is a realisation of a stochastic space–time process
- ▶ Space–time process is only **partly** described by a model of the temporal variation of the spatial mean
- ▶ Uncertainty about trend accounts for
  - ▶ random selection of sampling locations
  - ▶ stochastic space–time process

# D<sub>S</sub>M<sub>T</sub> approach

- ▶ In estimating the trend a stochastic time-series model for the spatial means is used, i.e. **model-based estimation**
- ▶ Space–time field is a realisation of a stochastic space–time process
- ▶ Space–time process is only **partly** described by a model of the temporal variation of the spatial mean
- ▶ Uncertainty about trend accounts for
  - ▶ random selection of sampling locations
  - ▶ stochastic space–time process



# D<sub>S</sub>M<sub>T</sub> approach

- ▶ In estimating the trend a stochastic time-series model for the spatial means is used, i.e. **model-based estimation**
- ▶ Space–time field is a realisation of a stochastic space–time process
- ▶ Space–time process is only **partly** described by a model of the temporal variation of the spatial mean
- ▶ Uncertainty about trend accounts for
  - ▶ random selection of sampling locations
  - ▶ stochastic space–time process

# Outline

Motivation and aim

Four statistical approaches in space–time

$D_S M_T$  approach

Estimation of Trend and its Variance

Case study

Conclusions

# Time–Series Model for Spatial Means



$$\bar{y}(t) = \sum_{j=1}^q \beta_j x_j(t) + \eta(t)$$

with  $\eta(t)$  the model error, mean 0 and covariance matrix  $\mathbf{C}_\xi$

- ▶  $\bar{y}(t)$  unknown, must be estimated:

$$\hat{\bar{y}}(t) = \sum_{j=1}^q \beta_j x_j(t) + \eta(t) + \varepsilon(t)$$

with  $\varepsilon(t)$  the sampling error, mean 0 and covariance matrix  $\mathbf{C}_p$

- ▶ If we take  $x_1(t) = 1$  and  $x_2(t) = t$ , then

$$\hat{\bar{y}}(t) = \beta_1 + \beta_2 \cdot t + \eta(t) + \varepsilon(t)$$

with  $\beta_2$  the linear trend parameter to be estimated

# Time–Series Model for Spatial Means



$$\bar{y}(t) = \sum_{j=1}^q \beta_j x_j(t) + \eta(t)$$

with  $\eta(t)$  the model error, mean 0 and covariance matrix  $\mathbf{C}_\xi$

- ▶  $\bar{y}(t)$  unknown, must be estimated:

$$\hat{\bar{y}}(t) = \sum_{j=1}^q \beta_j x_j(t) + \eta(t) + \varepsilon(t)$$

with  $\varepsilon(t)$  the sampling error, mean 0 and covariance matrix  $\mathbf{C}_p$

- ▶ If we take  $x_1(t) = 1$  and  $x_2(t) = t$ , then

$$\hat{\bar{y}}(t) = \beta_1 + \beta_2 \cdot t + \eta(t) + \varepsilon(t)$$

with  $\beta_2$  the linear trend parameter to be estimated

# Time–Series Model for Spatial Means



$$\bar{y}(t) = \sum_{j=1}^q \beta_j x_j(t) + \eta(t)$$

with  $\eta(t)$  the model error, mean 0 and covariance matrix  $\mathbf{C}_\xi$

- ▶  $\bar{y}(t)$  unknown, must be estimated:

$$\hat{\bar{y}}(t) = \sum_{j=1}^q \beta_j x_j(t) + \eta(t) + \varepsilon(t)$$

with  $\varepsilon(t)$  the sampling error, mean 0 and covariance matrix  $\mathbf{C}_p$

- ▶ If we take  $x_1(t) = 1$  and  $x_2(t) = t$ , then

$$\hat{\bar{y}}(t) = \beta_1 + \beta_2 \cdot t + \eta(t) + \varepsilon(t)$$

with  $\beta_2$  the linear trend parameter to be estimated

# GLS Estimation of Trend



$$\hat{\beta} = (\mathbf{X}'\mathbf{C}_{\xi p}^{-1}\mathbf{X})^{-1}(\mathbf{X}'\mathbf{C}_{\xi p}^{-1}\hat{\mathbf{y}})$$

with

$$\mathbf{C}_{\xi p} = \mathbf{C}_{\xi} + \mathbf{C}_p,$$



$$\text{Var}(\hat{\beta}) = (\mathbf{X}'\mathbf{C}_{\xi p}^{-1}\mathbf{X})^{-1}$$



$$\text{Var}(\hat{\beta}) = \text{Var}_{\xi} \left\{ \text{E}_p(\hat{\beta}) \right\} + \text{E}_{\xi} \left\{ \text{Var}_p(\hat{\beta}) \right\}$$

# GLS Estimation of Trend



$$\hat{\beta} = (\mathbf{X}'\mathbf{C}_{\xi p}^{-1}\mathbf{X})^{-1}(\mathbf{X}'\mathbf{C}_{\xi p}^{-1}\hat{\mathbf{y}})$$

with

$$\mathbf{C}_{\xi p} = \mathbf{C}_{\xi} + \mathbf{C}_p,$$



$$\text{Var}(\hat{\beta}) = (\mathbf{X}'\mathbf{C}_{\xi p}^{-1}\mathbf{X})^{-1}$$



$$\text{Var}(\hat{\beta}) = \text{Var}_{\xi} \left\{ \text{E}_p(\hat{\beta}) \right\} + \text{E}_{\xi} \left\{ \text{Var}_p(\hat{\beta}) \right\}$$

# GLS Estimation of Trend



$$\hat{\beta} = (\mathbf{X}'\mathbf{C}_{\xi p}^{-1}\mathbf{X})^{-1}(\mathbf{X}'\mathbf{C}_{\xi p}^{-1}\hat{\mathbf{y}})$$

with

$$\mathbf{C}_{\xi p} = \mathbf{C}_{\xi} + \mathbf{C}_p,$$



$$\text{Var}(\hat{\beta}) = (\mathbf{X}'\mathbf{C}_{\xi p}^{-1}\mathbf{X})^{-1}$$



$$\text{Var}(\hat{\beta}) = \text{Var}_{\xi} \left\{ \text{E}_p(\hat{\beta}) \right\} + \text{E}_{\xi} \left\{ \text{Var}_p(\hat{\beta}) \right\}$$



# Outline

Motivation and aim

Four statistical approaches in space–time

$D_S M_T$  approach

Estimation of Trend and its Variance

Case study

Conclusions

# Monitoring Soil Acidification in Forest Soils

- ▶ Four sampling rounds, interval one year
- ▶ Twenty locations per round
- ▶ Simple random sampling of 20 locations per round
- ▶ Rotational pattern, matching proportion 0.5
- ▶ Three sampling depths (depth depends on soil horizons)
- ▶ Four soil properties were measured: pH,  $\text{NO}_3$  ( $\text{mg kg}^{-1}$ ),  $\text{NH}_4$  ( $\text{mg kg}^{-1}$ ),  $\text{NO}_3$  ( $\text{mg l}^{-1}$ )

# Monitoring Soil Acidification in Forest Soils

- ▶ Four sampling rounds, interval one year
- ▶ Twenty locations per round
- ▶ Simple random sampling of 20 locations per round
- ▶ Rotational pattern, matching proportion 0.5
- ▶ Three sampling depths (depth depends on soil horizons)
- ▶ Four soil properties were measured: pH,  $\text{NO}_3$  ( $\text{mg kg}^{-1}$ ),  $\text{NH}_4$  ( $\text{mg kg}^{-1}$ ),  $\text{NO}_3$  ( $\text{mg l}^{-1}$ )

# Monitoring Soil Acidification in Forest Soils

- ▶ Four sampling rounds, interval one year
- ▶ Twenty locations per round
- ▶ Simple random sampling of 20 locations per round
- ▶ Rotational pattern, matching proportion 0.5
- ▶ Three sampling depths (depth depends on soil horizons)
- ▶ Four soil properties were measured: pH,  $\text{NO}_3$  ( $\text{mg kg}^{-1}$ ),  $\text{NH}_4$  ( $\text{mg kg}^{-1}$ ),  $\text{NO}_3$  ( $\text{mg l}^{-1}$ )

# Monitoring Soil Acidification in Forest Soils

- ▶ Four sampling rounds, interval one year
- ▶ Twenty locations per round
- ▶ Simple random sampling of 20 locations per round
- ▶ Rotational pattern, matching proportion 0.5
- ▶ Three sampling depths (depth depends on soil horizons)
- ▶ Four soil properties were measured: pH,  $\text{NO}_3$  ( $\text{mg kg}^{-1}$ ),  $\text{NH}_4$  ( $\text{mg kg}^{-1}$ ),  $\text{NO}_3$  ( $\text{mg l}^{-1}$ )

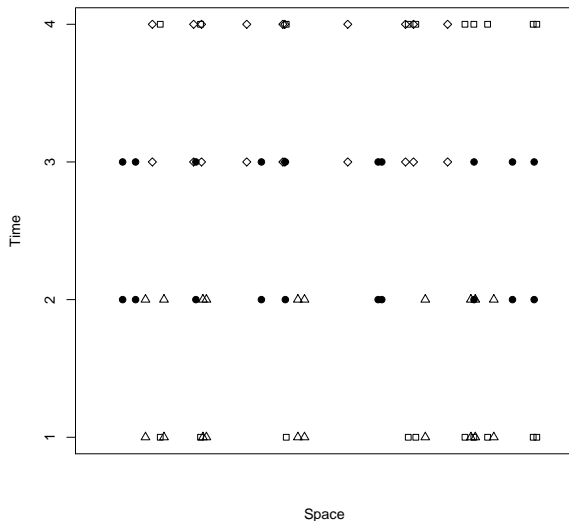
# Monitoring Soil Acidification in Forest Soils

- ▶ Four sampling rounds, interval one year
- ▶ Twenty locations per round
- ▶ Simple random sampling of 20 locations per round
- ▶ Rotational pattern, matching proportion 0.5
- ▶ Three sampling depths (depth depends on soil horizons)
- ▶ Four soil properties were measured: pH,  $\text{NO}_3$  ( $\text{mg kg}^{-1}$ ),  $\text{NH}_4$  ( $\text{mg kg}^{-1}$ ),  $\text{NO}_3$  ( $\text{mg l}^{-1}$ )

# Monitoring Soil Acidification in Forest Soils

- ▶ Four sampling rounds, interval one year
- ▶ Twenty locations per round
- ▶ Simple random sampling of 20 locations per round
- ▶ Rotational pattern, matching proportion 0.5
- ▶ Three sampling depths (depth depends on soil horizons)
- ▶ Four soil properties were measured: pH,  $\text{NO}_3$  ( $\text{mg kg}^{-1}$ ),  $\text{NH}_4$  ( $\text{mg kg}^{-1}$ ),  $\text{NO}_3$  ( $\text{mg l}^{-1}$ )

# Rotational pattern





# Estimation of variance-covariance matrix

- ▶ Estimation of sampling covariance

$$\text{Cov}_p(\hat{y}_i, \hat{y}_j) = \text{Cov}_p\left(\frac{m_{ij}}{n_i} \hat{y}_i^{(m)}, \frac{m_{ij}}{n_j} \hat{y}_j^{(m)}\right) = \frac{m_{ij}}{n_i n_j} S_{ij}^2$$

- ▶ We assumed model-independence of spatial means
- ▶ The model variance was estimated from the data, by tuning this variance in iterative fitting until:

$$\mathbf{e}' \mathbf{C}_{\xi p}^{-1} \mathbf{e} = df_{\text{res}}$$

# Estimation of variance-covariance matrix

- ▶ Estimation of sampling covariance

$$\text{Cov}_p(\hat{y}_i, \hat{y}_j) = \text{Cov}_p\left(\frac{m_{ij}}{n_i} \hat{y}_i^{(m)}, \frac{m_{ij}}{n_j} \hat{y}_j^{(m)}\right) = \frac{m_{ij}}{n_i n_j} S_{ij}^2$$

- ▶ We assumed model-independence of spatial means
- ▶ The model variance was estimated from the data, by tuning this variance in iterative fitting until:

$$\mathbf{e}' \mathbf{C}_{\xi p}^{-1} \mathbf{e} = df_{\text{res}}$$

# Estimation of variance-covariance matrix

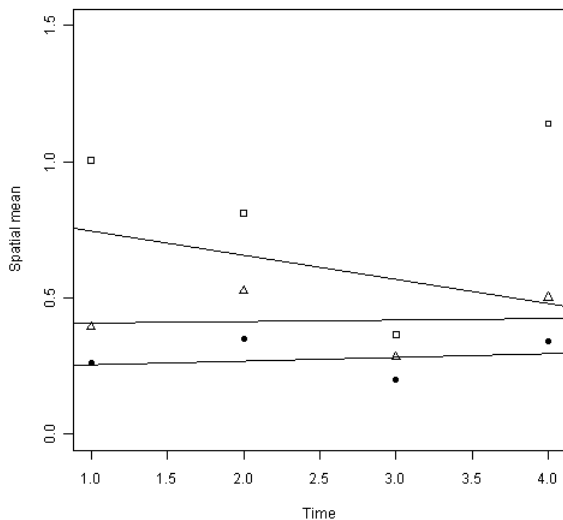
- ▶ Estimation of sampling covariance

$$\text{Cov}_p(\hat{y}_i, \hat{y}_j) = \text{Cov}_p\left(\frac{m_{ij}}{n_i} \hat{y}_i^{(m)}, \frac{m_{ij}}{n_j} \hat{y}_j^{(m)}\right) = \frac{m_{ij}}{n_i n_j} S_{ij}^2$$

- ▶ We assumed model-independence of spatial means
- ▶ The model variance was estimated from the data, by tuning this variance in iterative fitting until:

$$\mathbf{e}' \mathbf{C}_{\xi p}^{-1} \mathbf{e} = df_{\text{res}}$$

# Fitted trend for $\text{NO}_3$ ( $\text{mg N kg}^{-1}$ )



# Results

Depth	trend	se	$se_p$	$se_\xi$
top	-0.089	0.19	0.077	0.18
mid	0.0054	0.071	0.047	0.052
sub	0.014	0.043	0.030	0.030

# Outline

Motivation and aim

Four statistical approaches in space–time

$D_S M_T$  approach

Estimation of Trend and its Variance

Case study

Conclusions

# Advantages of $D_S M_T$ approach

Mixed, design-based model-based sampling approach can be an attractive alternative to fully model-based approach when data are **sparse** and interest is in **global space–time quantities** such as the temporal trend of the spatial mean:

- ▶ More simple
- ▶ Better validity
- ▶ More robust

# Advantages of $D_S M_T$ approach

Mixed, design-based model-based sampling approach can be an attractive alternative to fully model-based approach when data are **sparse** and interest is in **global space–time quantities** such as the temporal trend of the spatial mean:

- ▶ More simple
- ▶ Better validity
- ▶ More robust



# Advantages of $D_S M_T$ approach

Mixed, design-based model-based sampling approach can be an attractive alternative to fully model-based approach when data are **sparse** and interest is in **global space–time quantities** such as the temporal trend of the spatial mean:

- ▶ More simple
- ▶ Better validity
- ▶ More robust

Thanks for your attention