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Nieuwenhuizen, Ard T.¹, J.W. Hofstee², E.J. van Henten^{2,3}, J.C. van de Zande¹

Precision detection and spraying of volunteer potato plants in sugar beet fields

¹ Field Technology Innovations, WUR, Plant Research International, P.O. Box 616, 6700 AP Wageningen, The Netherlands; ² Farm Technology Group, Wageningen University, P.O. Box 17, 6700 AA Wageningen, The Netherlands; ³ Wageningen UR Greenhouse Horticulture, P.O. Box 16, 6700 AA Wageningen, The Netherlands

E-mail contact: ard.nieuwenhuizen@wur.nl

Volunteer potato plants are a major weed problem in Western European cropping rotations. They are a source for the spread of disease, nematodes, and pests. For example they spread *Phytophthora infestans*, that causes late blight in potato crops. However, the control of *Phytophthora infestans* requires large amounts of pesticides that farmers, environmental groups, and politicians want to reduce. This is stressed by the framework directive on the sustainable use of pesticides, EU directive 2009/128/EC. Therefore, adequate control of volunteer potato plants and weeds is required. Volunteer plants are best controlled by application of glyphosate. This ensures control of haulm and tuber, and re-growth is inhibited. Currently available machines have a high risk of sugar beet crop injury and have a high labour demand, requiring a practical innovative solution. The stakeholders of the problem asked for a solution and an automated precision detection and spraying system was designed and tested.

With machine vision a plant specific detection system was made. Real time algorithms detect up to 1 m s⁻¹ travel speed with a resolution of 1 cm² for three sugar beet rows where glyphosate has to be applied onto volunteer plants. After detection of individual potato plants in the sugar beet row, a micro sprayer applies targeted droplets of gel and glyphosate onto the weeds. A gel instead of water was used because no splash and drift to adjacent crop plants is allowed.

The prototype system that integrated real-time detection and targeted individual droplets at volunteer plants was tested in experimental fields. In one of the fields 96.6% volunteer potato classification and 8.0% sugar beet misclassification was achieved. In an experiment where also the sprayer was activated, over 80% of the weed potato plants were destroyed and only up to 2% of the sugar beet plants were destroyed, mainly due to incorrect detection, not as a result of spray drift. The precise positioning of droplets facilitates further developments into precision application of nutrients and pesticides on crops and weeds in agricultural fields.